

3D Videogames
Università degli Studi di Milano



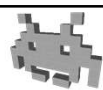
Rendering in 3D games


Part I: lighting environments



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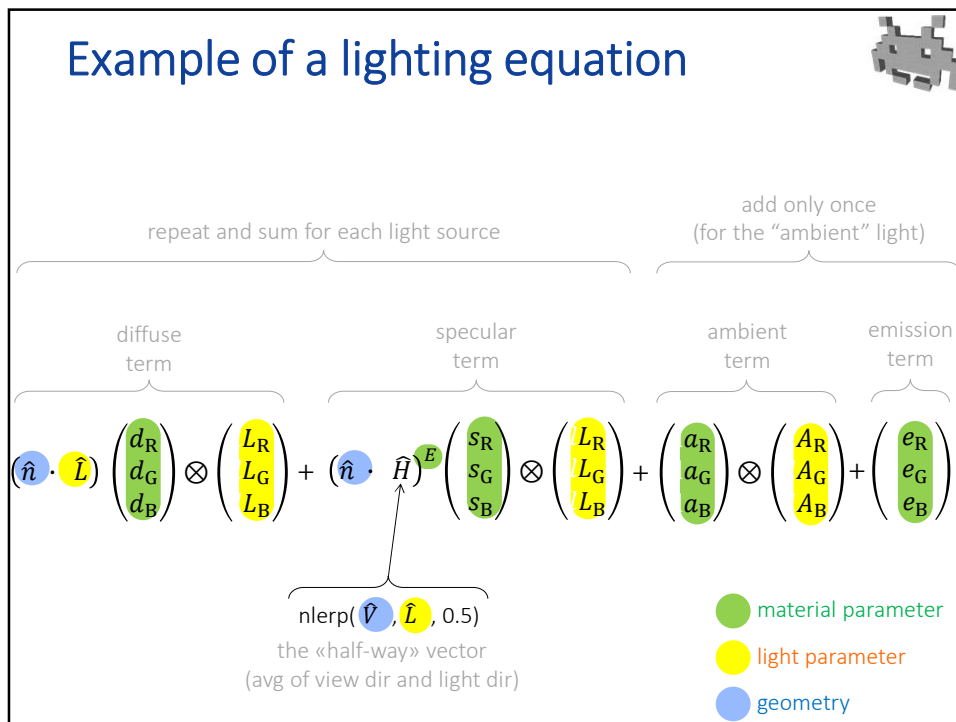
Course Plan



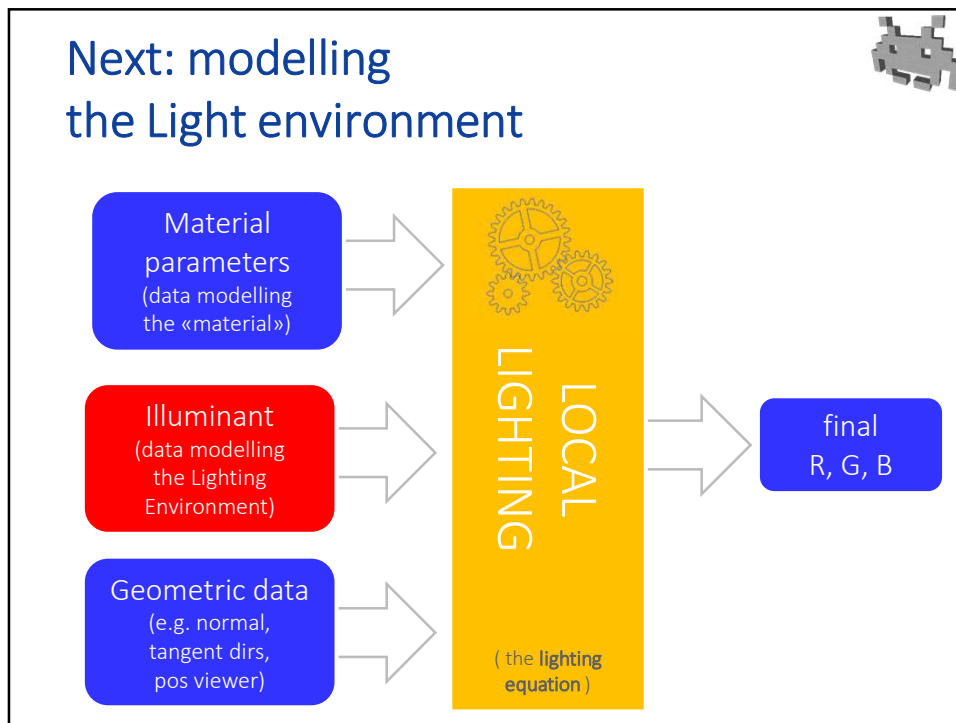
- lec. 1: **Introduction** ●
- lec. 2: **Mathematics** for 3D Games ●●●●●●
- lec. 3: **Scene Graph** ●
- lec. 4: **Game 3D Physics** ●●●●+●●
- lec. 5: **Game Particle Systems** ◐
- lec. 6: **Game 3D Models** ◐●
- lec. 7: **Game Textures** ●●
- lec. 9: **Game Materials** ◐
- lec. 8: **Game 3D Animations** ◐●●●
- lec. 10: **Networking** for 3D Games ◐
- lec. 11: **Artificial Intelligence** for 3D Games ●
- lec. 12: **3D Audio** for 3D Games ●
- lec. 13: **Rendering Techniques** for 3D Games ● 

For a more general, deeper discussion of many of the subjects of this lecture, see the courses
CG
«Computer Graphics»
and
RTGP
«Real-Time Graphics Programming»

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Approaches to model the light environment in 2D games

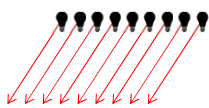


We are about to discuss three ways:

- **Discrete**
 - a finite set of individual **light sources** (including one global **ambient factor** for the “leftovers”)
 - **Densely sampled**
 - **environment maps**: textures sampling incoming light
 - **Basis functions**
 - a spherical function stored as **spherical harmonics** coefficients
- (They can be used jointly)

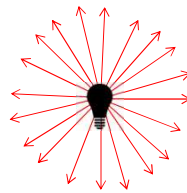
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Discrete illumination environments. A set of light sources:



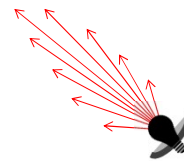
directional light

- intensity / color
- direction



point lights

- intensity / color
- position
- falloff function (opt.)

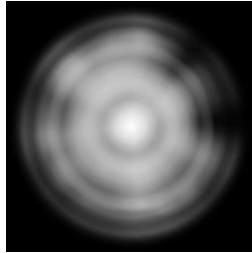


spot-lights

- intensity / color
- position
- direction
- falloff function (opt.)
- angular falloff funct.
- “cookie” texture

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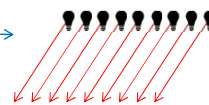
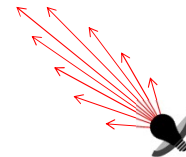
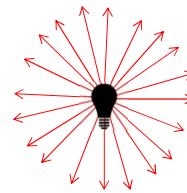
Cookie texture (for spot-lights)



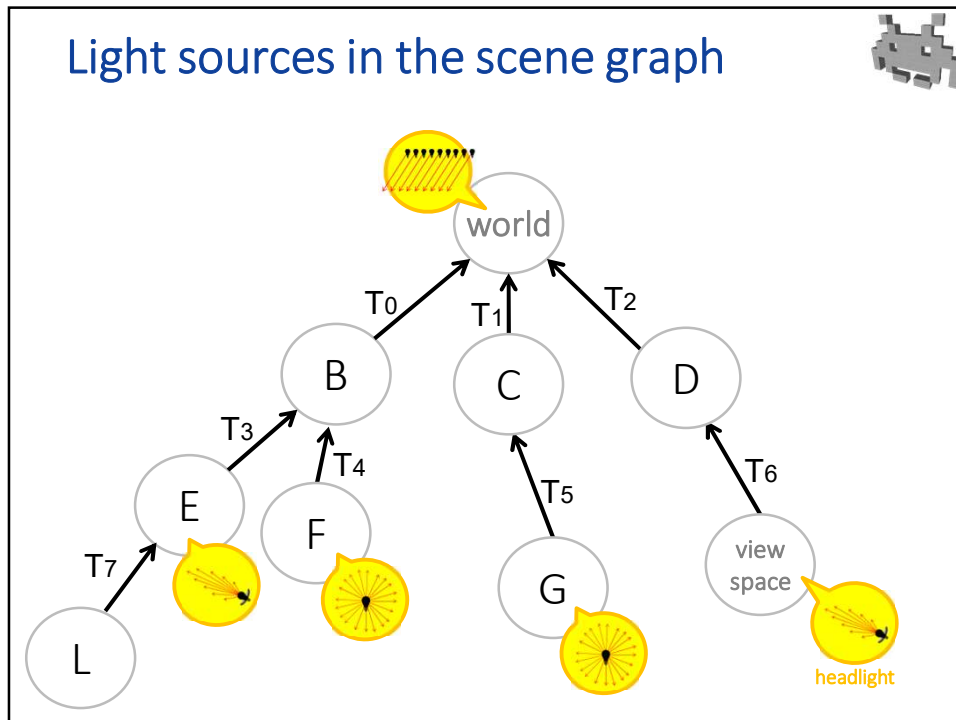
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Illumination environments: discrete

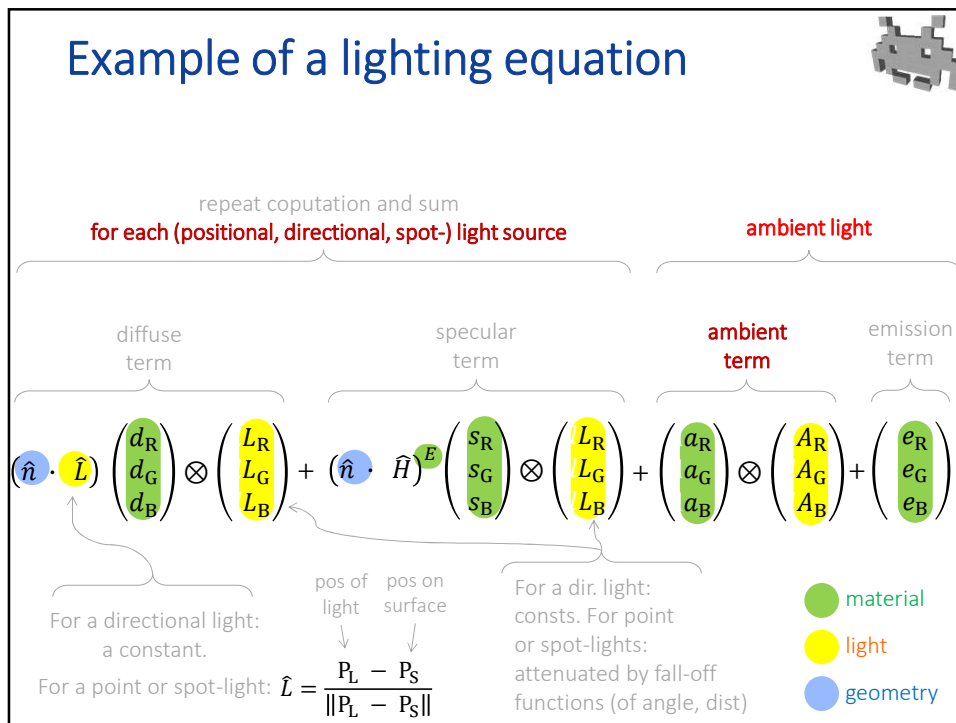
- a finite set of “light sources” ...
 - not many (e.g. ≤ 16)
- each one sitting in a node of the scene-graph
- each of a type:
 - **point light sources**
 - have: position
 - **spot-lights**
 - have: position, orientation, wideness (angle)
 - **directional light sources**
 - have: orientation only
- with attributes such as:
 - color / intensity
 - fall-off function (with distance)
 - max range, and more



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Discrete illumination environments



- Pros:
 - simple to position / reorient individual light sources
 - both at design phase, or dynamically (at game exec)
 - good model of illuminants, such as:
 - explosions (positional lights)
 - car lights (spot-lights lights)
 - sun direction (directional light)
 - relatively easy to compute (hard, soft) shadows for them
- Cons:
 - each light source requires extra processing ... for each pixel!
 - therefore: hard limit on their number. Prioritize
 - therefore: are often given a (physically unjustified) radius of effect
 - they don't model well:
 - area light sources (e.g., from back-lit clouds)
 - reflections on (metal) objects

main illuminants
of the scene!

see
shadow
map
later

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Discrete illumination environments



a finite set of "light sources":

- A number of (directional | positional | spot-) lights
- Plus, one global **"ambient light" factor**
 - models other minor light sources + bounces
 - light incoming "from every direction at every position"
 - it's a distinct term in the lighting equation
 - examples:
 - in an overcast outdoor scene: *high*
 - (dim shadows, flat looking lighting: every photographs' favorite for portraits!)
 - in realistic outer space: *zero*
 - in any other scenes : *something in between* (e.g., sunny day, or torch-lit cave)

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Densely sampled illumination environments

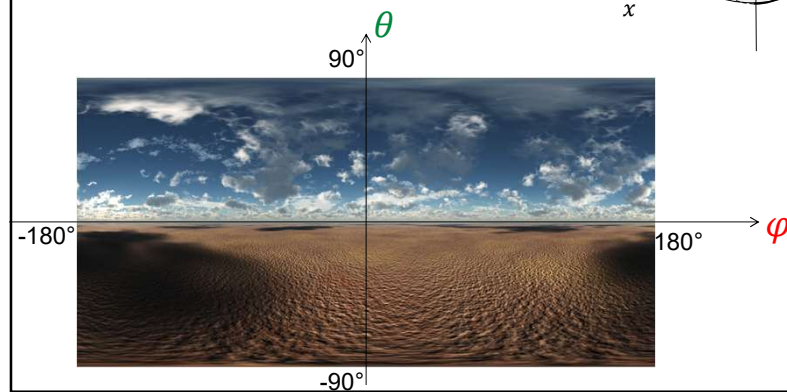
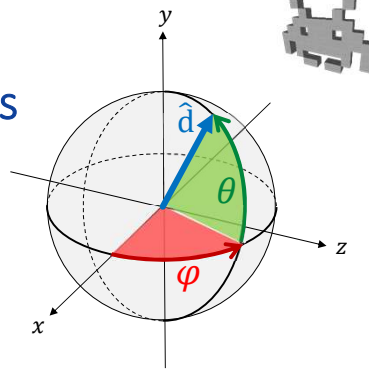
- A light intensity / color from each direction \hat{d}
- Asset to store that:
“Environment map” texture



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Densely sampled illumination environments


- Latitude/longitude format
(of a unit vector \hat{d})



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Densely sampled illumination environments


- Aka “sky-map” texture
 - when it’s only / predominantly the sky to be featured
 - doubles as textures for “sky boxes”

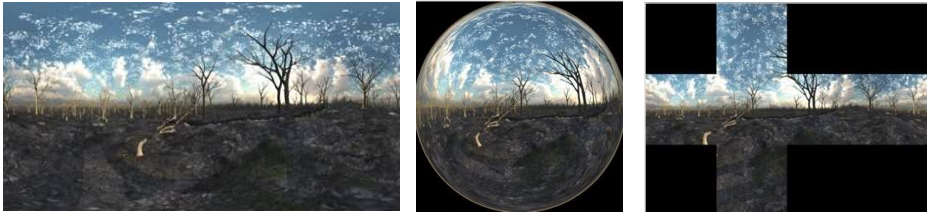


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Densely sampled illumination environments

- **Environment map:** (asset)
a texture with a texel t for each direction \hat{d}
 - t stores the intensity/color of the light coming from direction \hat{d}
- Q: how to find u, v position of t for a given \hat{d} ?
 - i.e. how to parametrize (flatten) the unit sphere
- Different answers are possible...

unit vector \hat{d} 



latitude/longitude format mirror sphere format cube-map format (ad-hoc HW support!)

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Environment map (asset)

- A texture with a texel t for each direction \hat{d}
 - t stores the light coming from direction \hat{d}
 - useful to compute reflections on (curved) metallic objects
 - often HDR (see later)
- Pro: realistic, complex, detailed, hi-freq, light env
 - best for mirroring materials (such as metal, glass, water)
- Pro: can be captured from reality
 - see “mat-cap”
- Con: expensive to update for dynamic scenes
 - no prob, for static environments only
- Con: assume far away illuminants
 - Not accurate for close illuminant



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Environment map (asset): uses

1. Reflection mapping
 - metallic objects
 - material roughness \rightarrow mipmap level!



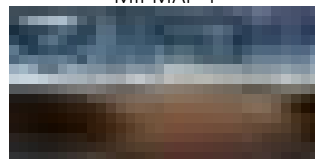
Roughness 0
MIPMAP 0



Roughness 0.25
MIPMAP 2



Roughness 0.5
MIPMAP 4



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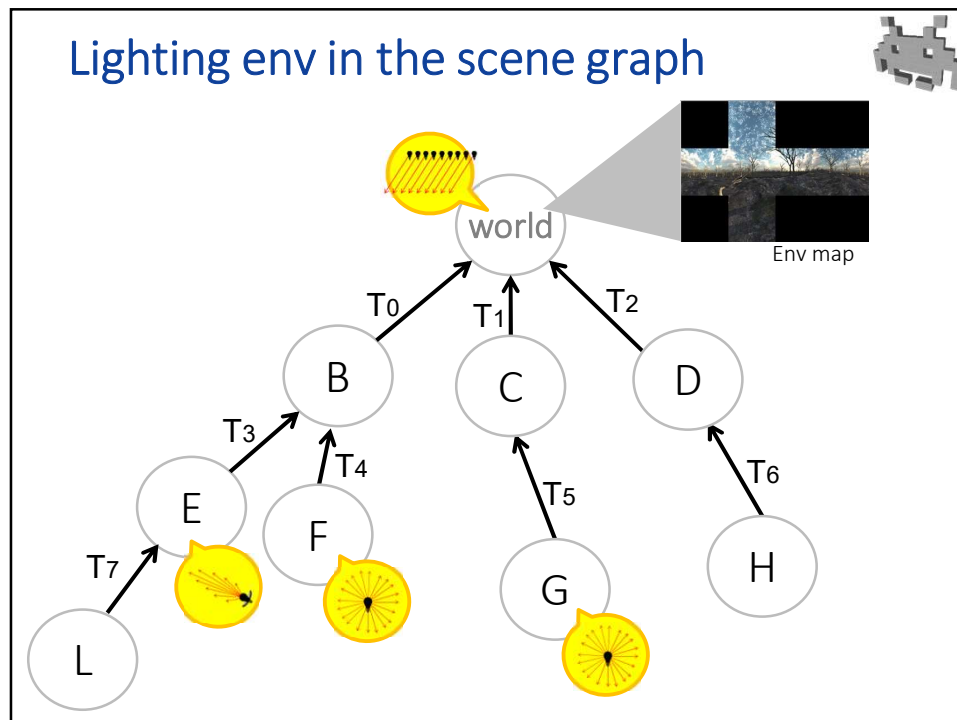
Environment map (asset): uses

1. Reflection mapping
 - metallic objects
 - material roughness → mipmap level!
2. More generally, description of the lighting env
 - for lighting computation
3. Coverage of the background
 - e.g., as a texture for the 3D sky-box / sky-dome



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Lighting env in the scene graph



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Light environments: using Basis Functions

- Lighting environment:
a *continuous* function $f : \Omega \rightarrow \mathbb{R}$
- $f(\hat{v})$ = amount of (rgb) light coming from direction \hat{v}
- Store f through basis functions

set of all unit vectors
(i.e., surface of the unit sphere)

or \mathbb{R}^3 if RGB
colored light

















fixed spherical "basis" functions (always the same ones)


$$f(\hat{v}) \cong a_{0,0} \cdot f_{0,0}(\hat{v}) + a_{1,-1} \cdot f_{1,-1}(\hat{v}) + a_{1,0} \cdot f_{1,0}(\hat{v}) + a_{1,+1} \cdot f_{1,+1}(\hat{v}) + \dots$$

a few scalar values to be stored, in order to represent (an approx. of) f

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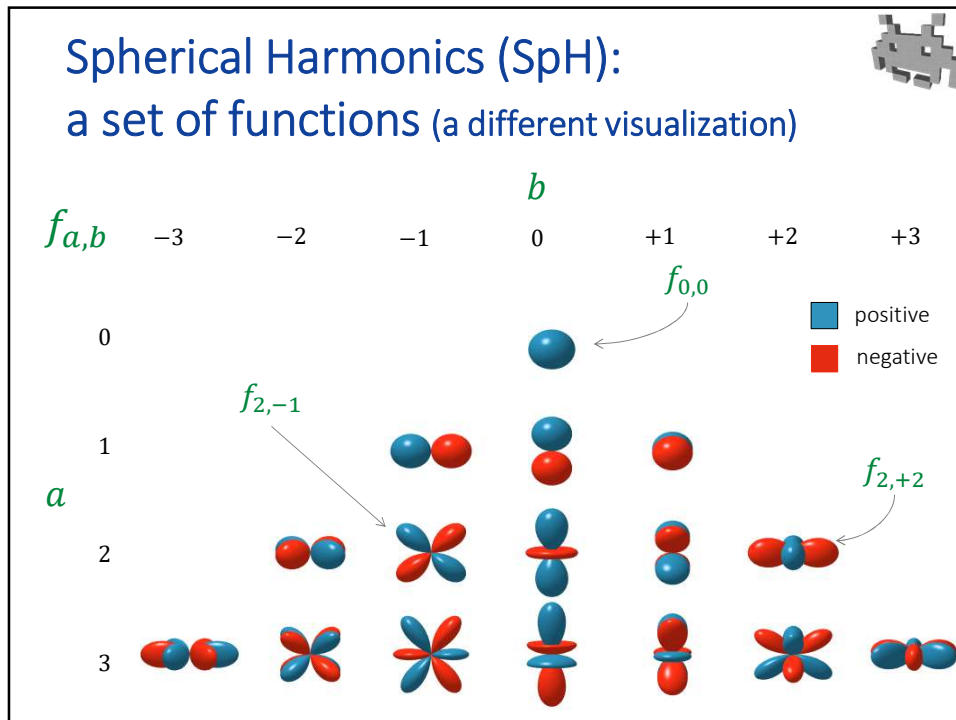
Spherical Harmonics (SpH): a set of functions

	$f_{a,b}$	-3	-2	-1	0	+1	+2	+3
0								
1								
2								
3								



+1
0
-1

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Spherical Harmonics (SpH): a good choice for the basis functions

- Spherical Harmonics is a good set of basis functions for spherical functions
- Each function in the set has two indices a, b
 - $f_{a,b}(\hat{v})$ with $a \geq 0, -a \leq b \leq +a$
 - $f_{0,0}(\hat{v}) = 1$ a constant function (so, scalar $a_{0,0}$ represent the *total amount* of light)
 - all other basis function sum up to 0 (i.e., their integral over Ω is zero) so, they control the distribution not the *quantity*, of light
 - they are designed to have useful mathematical properties (e.g., orthogonality – the integral of the product of any two is 0)
 - all SpH functions are easy to compute, e.g. integrate, etc

the degree \rightarrow

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Light probes: Light environment stored with SpH

stored, i.e., the representation of (grayscale) LIGHT ENV as Spherical Harmonics

$$f(\hat{v}) \cong +0.5 \cdot f_{0,0} + 0.9 \cdot f_{1,-1} - 0.7 \cdot f_{1,0} + 0.3 \cdot f_{1,+1} + 0.1 \cdot f_{2,-2} + \dots$$

fixed, immutable, closed form functions that are easy to compute and manipulate

f is stored as $(+0.5, +0.9, -0.7, +0.3, 0.1, \dots)$

(if it's a colored Light Env, this is repeated for each R,G,B channel)

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Light probes: Light environment stored with SpH

- Spherical Harmonics (SPH) in brief:
 - store Illumination Env as a small number (4,9,16...) of scalar **weights** of as many fixed **spherical basis functions**.
- Pros:
 - very compact representation
 - it models continuous functions well: good for smooth lighting environments
 - it allows for efficient computation of the Lighting equation
 - it's easy to interpolate between light envs!
- Cons:
 - continuous functions *ONLY*
 - Not good for hi-freq details: for example, no hard lights
 - not sudden variations (unless very many coefficient used)
- Good for soft light env

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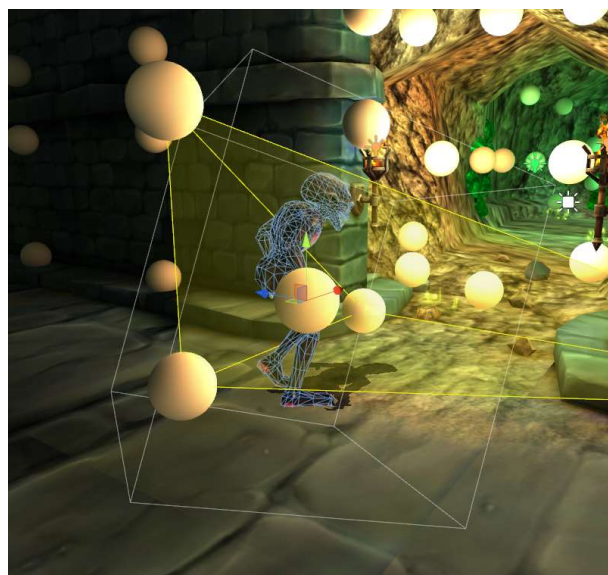
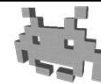
Light probes (position-dependent lighting env)



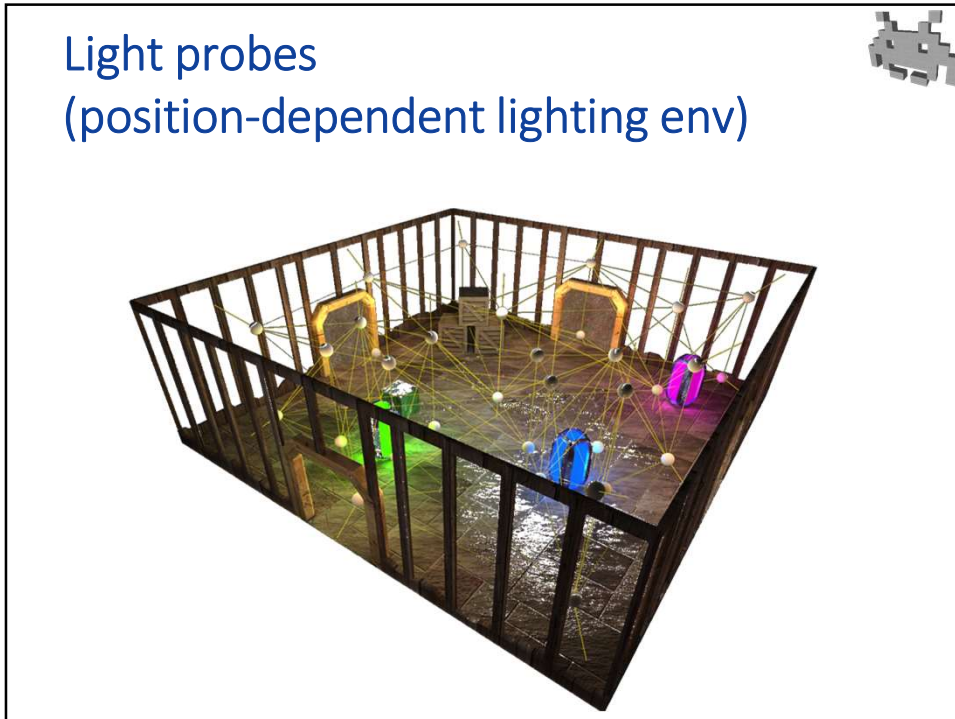
- A light probe == a (precomputed) lighting env. to be used around a given 3D position of the scene
- Light Probe lighting:
 - preprocessing: disseminate the scene with light probes
 - Store them as... low-res environment maps
 - ...or, with SPH (the standard solution)
 - at rendering time, for an object currently in pos (xyz), use an **interpolation** of near-by "light probes"
 - note: two (or more) SPH function can be interpolated!
 - easy: just interpolate the weights

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Light probes (position-dependent lighting env)



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Illumination-driven Light Probe Placement

K. Vardis¹ and A. A. Vasilakis¹ and G. Papaioannou¹
Department of Informatics, Athens University of Economics and Business

Light Probes

- Light probes help encode and represent global illumination for real-time rendering.
- Placement is typically performed as either an automatically laid-out grid or manually...

Observations

- Placement should depend on the lighting distribution itself!
- Colour bleeding dominated by chrominance
- Indirect shadows translate to mostly luminance transitions

Our Method

Goal

- Lighting driven probe placement
- A simple and generic method

Two-step algorithm

- Setup:** Generate dense reference probes and supply light field evaluation points
- Simplification:** Iteratively remove least important probes using mean absolute percentage error

Illumination criteria

- Transform radiance to YCoCg and
- Guide simplification according to weighted YCoCg components for chrominance/luminance-based preference

Setup

Place N Light Probes → Compute Radiance Field → Place M Evaluation Points → Calculate Radiance Field Evaluation Reference

Simplification

Select Light Probe Candidates → Compute New Evaluation Cost → Output least important Light Probe → Repeat until user reached N-1 configurations

Results

Initial Light Probes | **Evaluation Points**

Lighting setup A: Similar light source colors

Luminance-driven: 53% probes left, 3% error

Lighting setup B: Contrasting light source colors

Chrominance-driven: 65% probes left, 3% error

Source code: github.com/cgueb/light_probe_placement
AUEB CGG: graphics.cs.aueb.gr

Public Venue Awards

Keynote O'Sullivan | Closing Session | Eurographics 2021

EUROGRAPHICS 2021 MAY 31 - JUNE 4, 2021

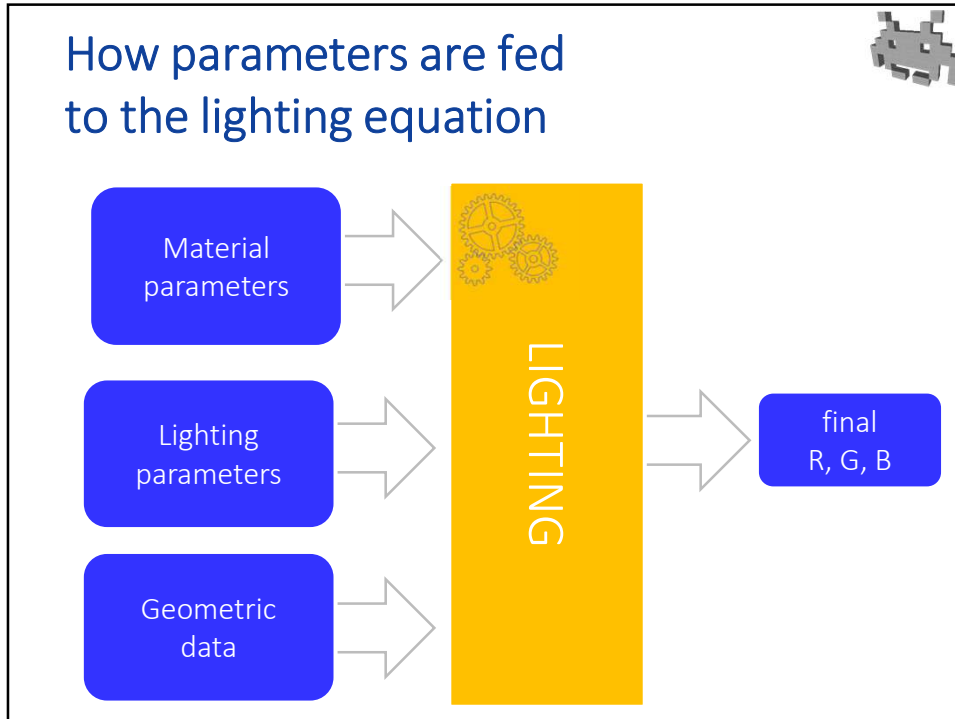
Top chat

- Yrissa Augsponner
- Wouter
- Jiri Dittler
- Khrystyna Vasylenko
- Emilie Yu
- Reinhold Preiser
- Gitta Domik
- Seth Banaga
- Noeska Smit
- Vulker Setgast
- Marco Tarini: that fast forward "is" amazing
- Carol O'Sullivan
- Johanna Schmidt
- Alexander Komar
- Reinhold Preiser: congrats!
- Kostas Vardis: Thank you!
- Marco Tarini: say something...

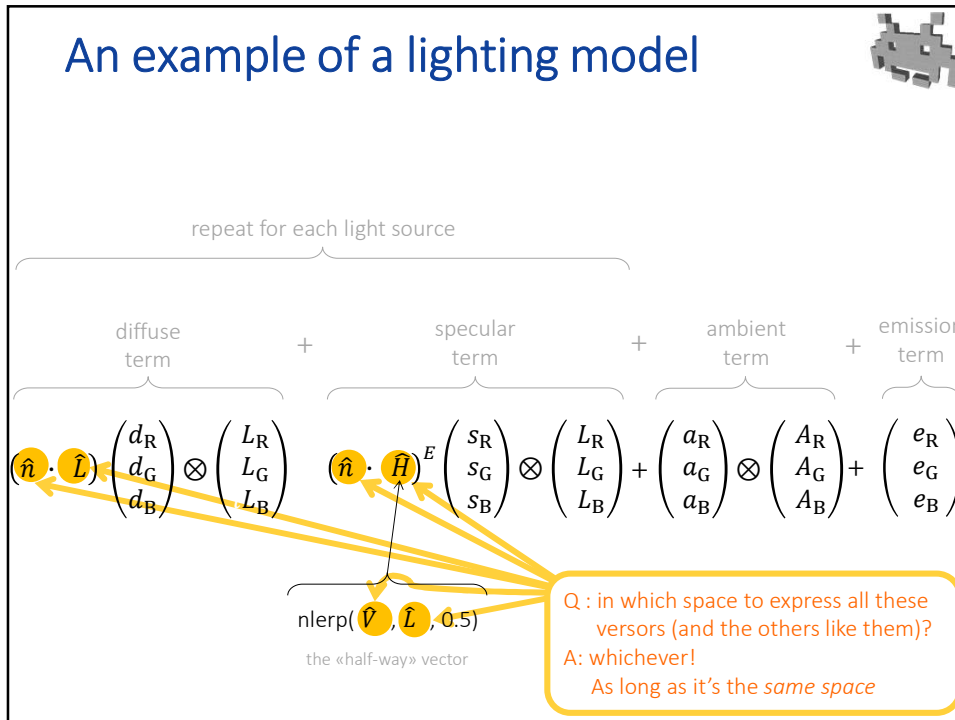
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Recently uploaded | Watched

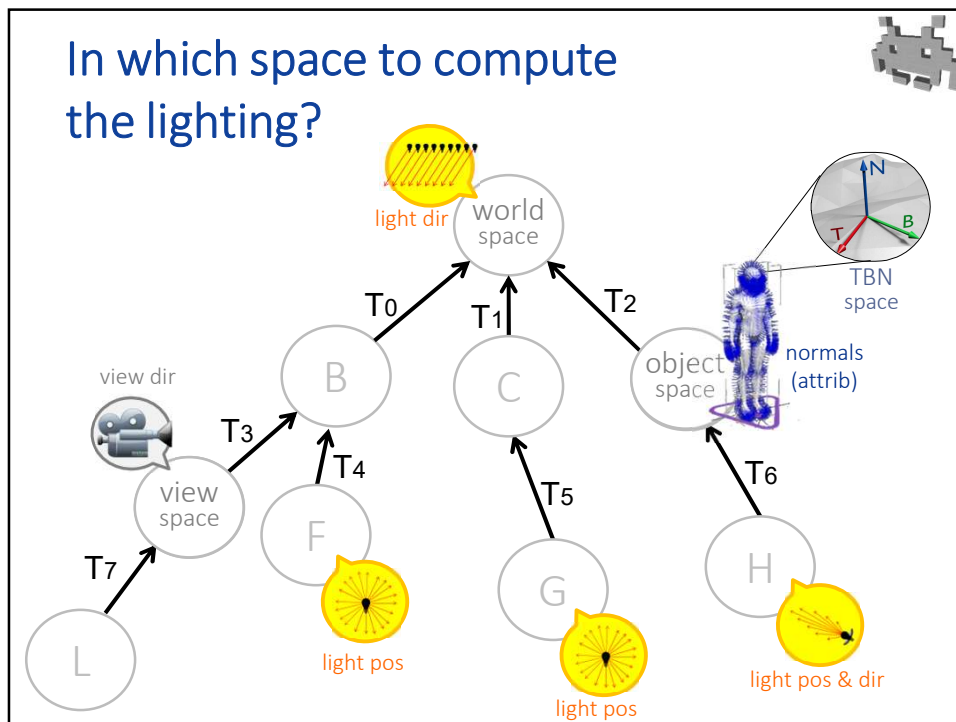
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In which space to compute the lighting?

- All **versors** that used in any operation in the **lighting equation** must be expressed in the **same space**
 - view direction, light directions, half-way vector, normals, tangent dirs...
- Choice: which space to use?
 - View space? (the space of the camera)
 - World space?
 - Local object space? (the space of the object currently being rendered)
- With normal maps, usually the most efficient solution is:
 - Use the same space the normals are expressed
 - For normal stored as attribute: the Local Space (aka Object Space)
 - For Tangent Space normal maps: in the the TBN space. Then...
 - ...all other versors must be transformed into this space, *per vertex!*
 - ...the normals accessed from the texture can be used right away, *per pixel!*
 - This minimizes the amount of transformations needed

↑
for anisotropic materials

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Rendering task for in 3D games:
overview

- Real time
 - (20 or) 30 or 60 FPS
- Hardware (GPU) based
 - pipelined, stream processing
- therefore: one class of algorithms (hardwired)
 - **rasterization** based algorithm
 - recent trend: switch to **ray-tracing** algorithms?
- Complexity:
 - Linear with # of primitives
 - Linear with # of pixels

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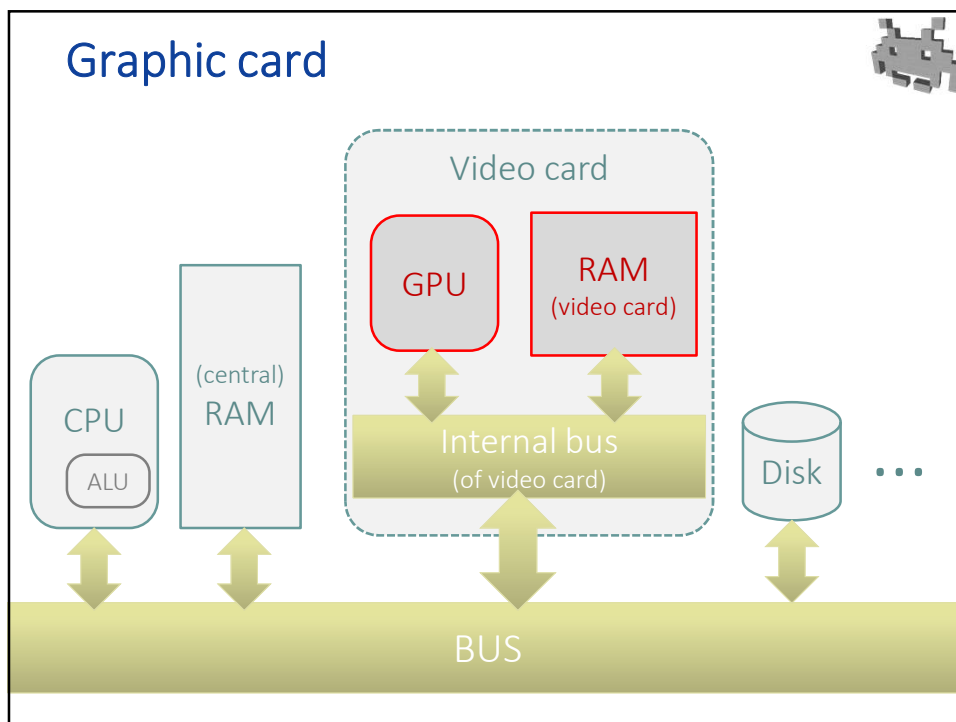
High-level view of mesh rendering

To render a mesh:

- load in **GPU RAM**:
 - ✓ Geometry + Attributes
 - ✓ Connectivity
 - ✓ Textures
 - ✓ Vertex + Fragment Shaders
 - ✓ Global Material Parameters
 - ✓ Rendering Settings
- issue the **Draw-call**

For this lecture, we need go lower level (a bit)

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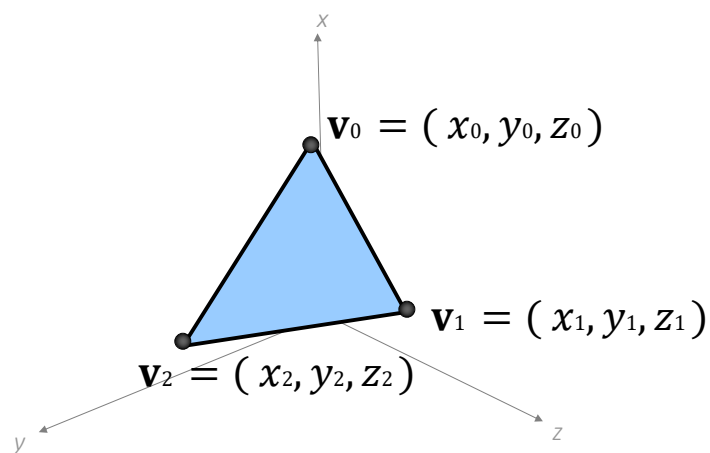
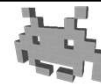
This lecture: a bird-eye view on...



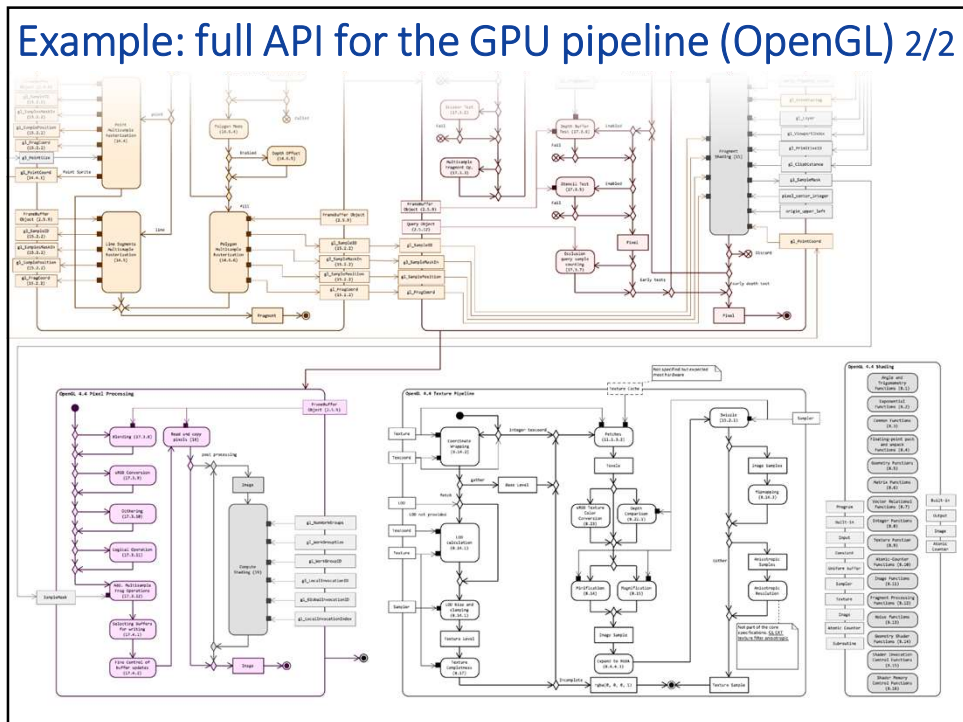
- Basics of GPU-based rendering
 - a brief summary of rasterization based rendering
 - programmable parts of the pipeline
 - depth-maps
 - double buffering
- Rendering techniques & tricks used in games
 - Multi-pass techniques in general
 - Deferred shading
 - Screen space techniques in general
 - A summary of a few common CG techniques

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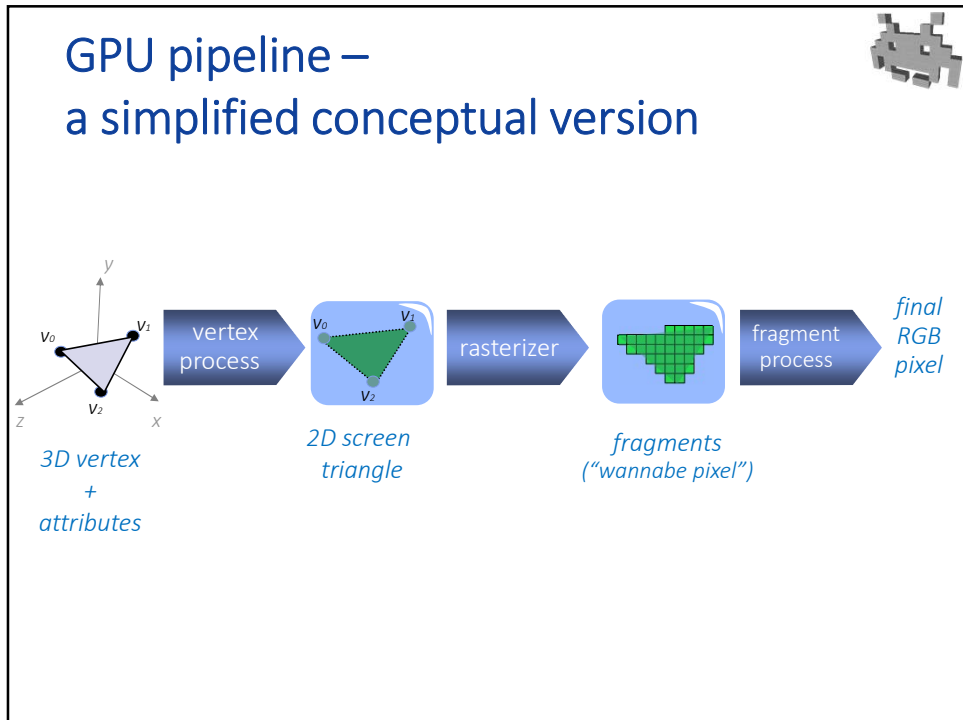
Rendering of a mesh = rasterization of all its triangles



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Rasterization based rendering: steps (remarks 1/2)



- **Vertex processor: (per vertex)**

- Input: vertex data (position + initial attributes)
- Output: a final screen position, and other (refined) attributes

It's a **SIMD architecture**:

Every step does the same processing on several input producing several output, all in parallel,

- **Rasterizer: (per triangle)**

- Input: a triplet of processed vertex (with attributes)
- Output: many "fragment", one for each pixel covered by the triangle, each with interpolated attributes

- **Fragment shader: (per fragment)**

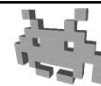
- Input: a fragment (with attributes)
- Output: a final rgb color (plus: an alpha value, plus: a depth value)

- **Output combiner: (per fragment)**

- Writes the rgb color on the screen buffer
- Overwrites, blends, or preserves the old value

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Rasterization based rendering: steps (remarks 2/2)



- It's a **pipelined architecture**:

every step works in parallel with all others

- E.g., while fragment are processed, the next triangle is being rasterized, and the next vertices are processed

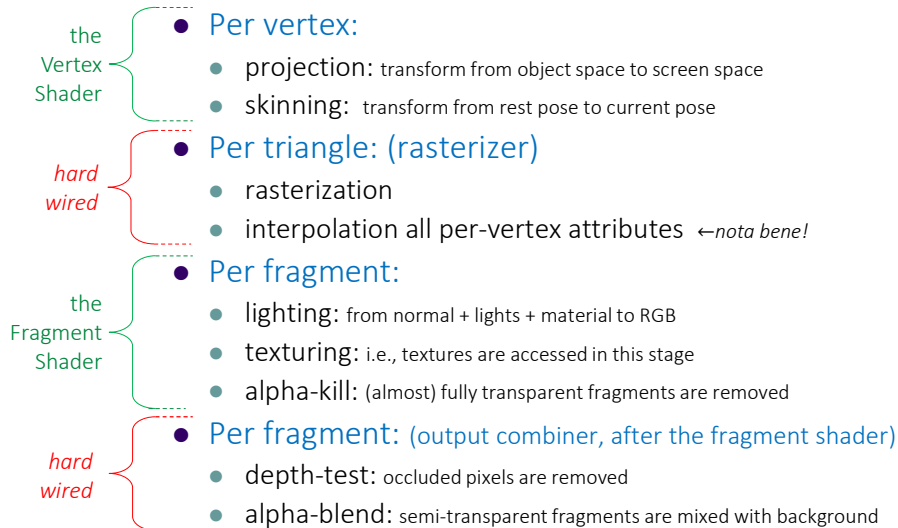
- It's a **SIMD architecture**:

Every step does the same processing on several inputs, producing several output, all in parallel,

- E.g., several fragments are processed at the same time (each one independently from the others)
- E.g., same for vertices

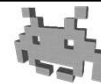
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Rasterization based rendering: what is done in each step (examples)



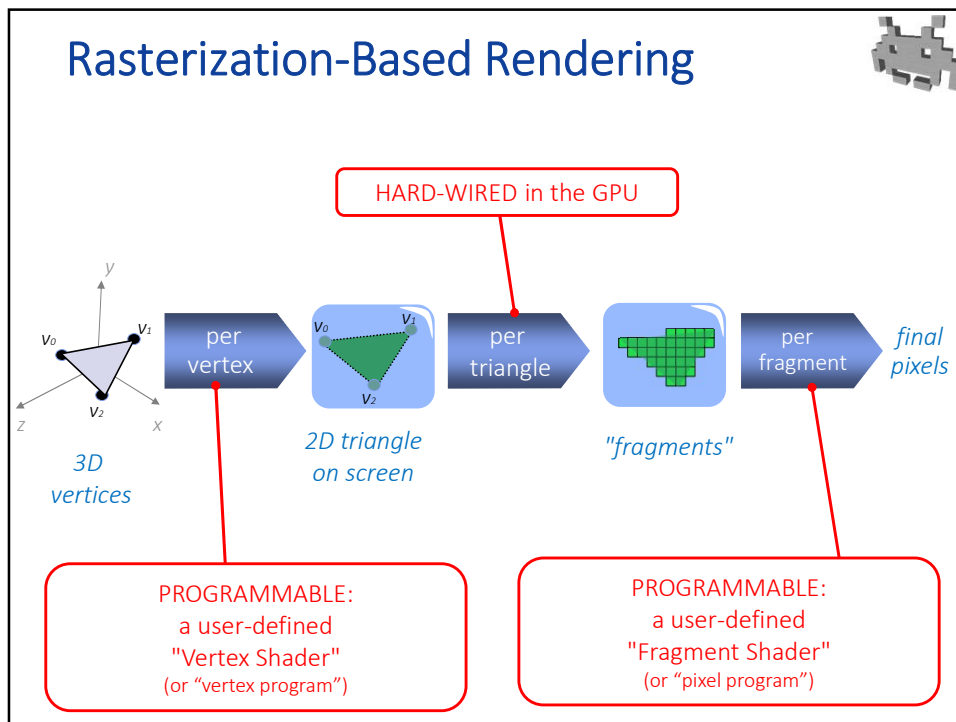
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GPU pipeline – bottlenecks (remarks and terminology)

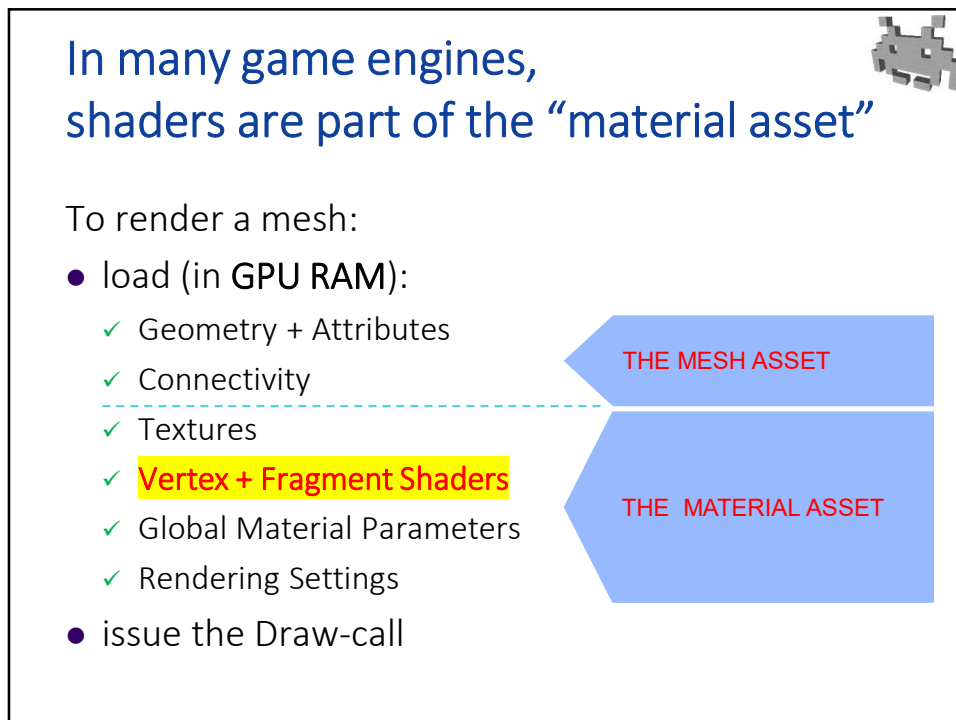


- Like in any pipeline, the process goes *as slow as its slowest stage*
 - i.e., the «bottleneck» of the pipeline determines the total speed
 - Any other stage is idle for part of the time (which is always a waste)
 - stages before the bottleneck are «choked» (they cannot produce output because next stage is not ready)
 - stages after it are «starved» (they wait for input from previous stage)
 - Bottleneck terminology: (in CG)
 - If the bottleneck is per vertex, the app is **geometry-limited** («it cannot process geometry fast enough»)
 - If the bottleneck is per fragment, the app is **fill-limited** («it cannot fill the screen buffer with pixel fast enough»)
 - Performances (rendering FPS) of a game only improves if computational load is removed from the bottleneck phase
 - Example: using all meshes at LOD 1 instead of one does not help a fill-limited app
 - Example: reducing the resolution of the screen does not help a geometry-limited app
 - Using a simpler lighting model does not help a geometry-limited app
- MORE COMMON CASE, FOR GAMES

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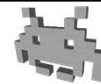
Programming languages for writing shaders



- High level:
 - **HLSL** (High Level Shader Language, Direct3D, Microsoft)
 - **GLSL** (OpenGL Shading Language)
 - **CG** (C for Graphics, Nvidia)
 - **PSSL** (PlayStation, Sony)
 - **MSL** (Metal, Apple)
- Low level:
 - **ARB** Shader Program
(the “assembler” of GPU – now deprecated)

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Depth buffer (or Z-buffer) (or depth-map)

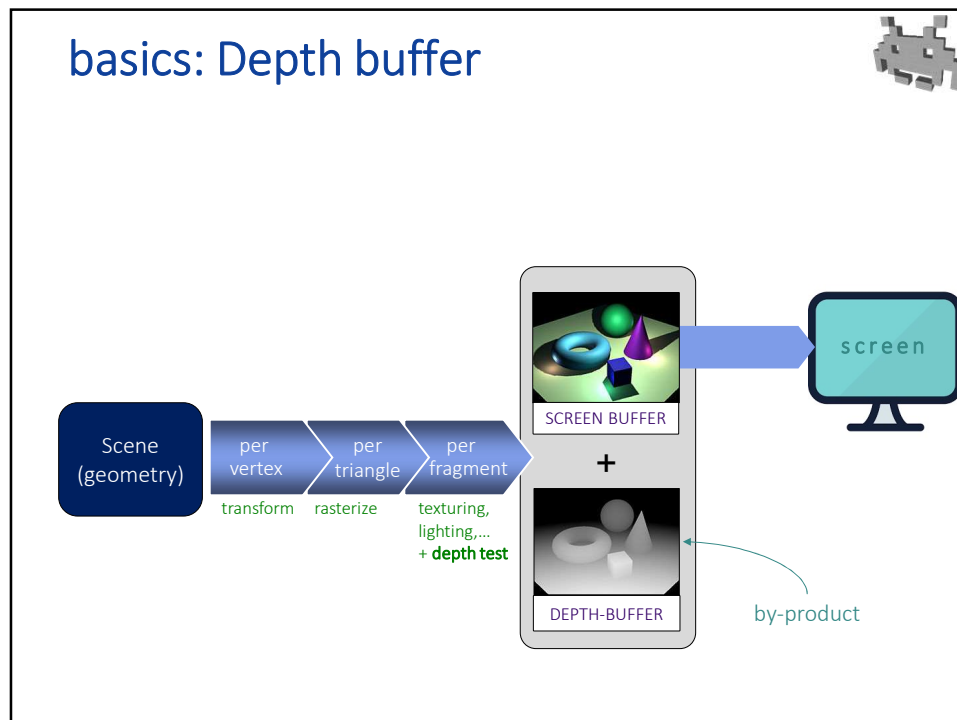


- Any rendering producing a **screen-buffer** ...
 - which is sent to the screen
- ...also produces a **depth-buffer**
 - as a by-product!
 - not set to the screen: it’s an “offline” buffer
 - it’s used during the rendering to determine occlusions and remove “hidden surfaces”
(i.e. make what is behind something else is not seen, because it’s covered by that something)
 - see computer graphics course for more details
- many rendering algorithms exploit the depth-buffer
 - for different uses
 - for each pixel on the screen, we have not only its RGB value, but its depth value (a scalar from 0 – close to the camera, to 1 – far from the camera)

a 2D array
of **RGB values**
of some
resolution

a 2D array
of **depth values**
(scalars in 0 to 1)
of the
same resolution

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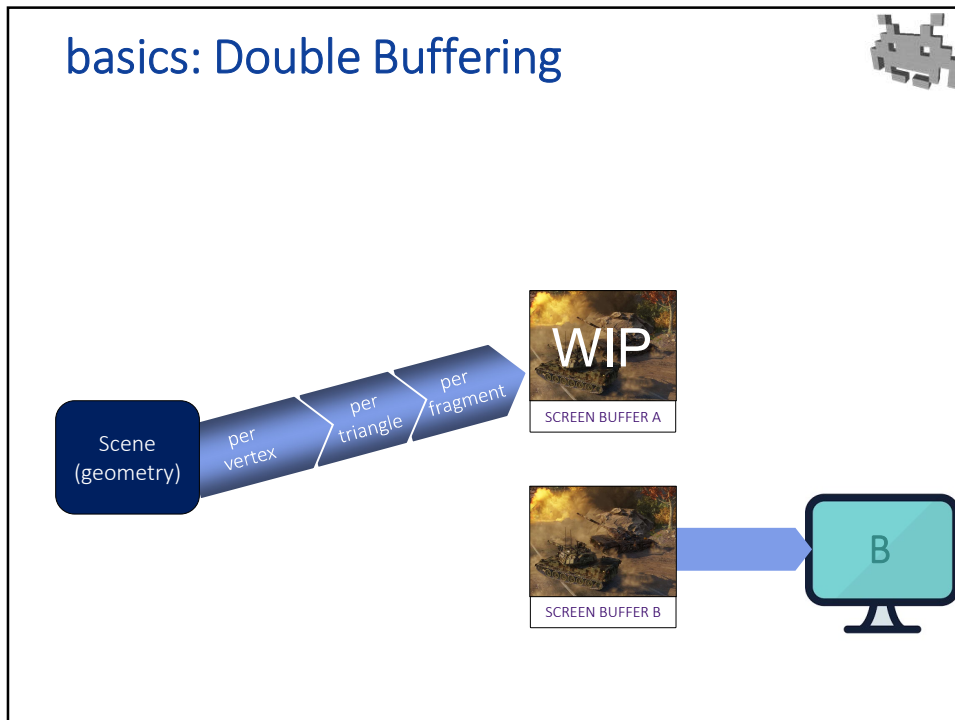


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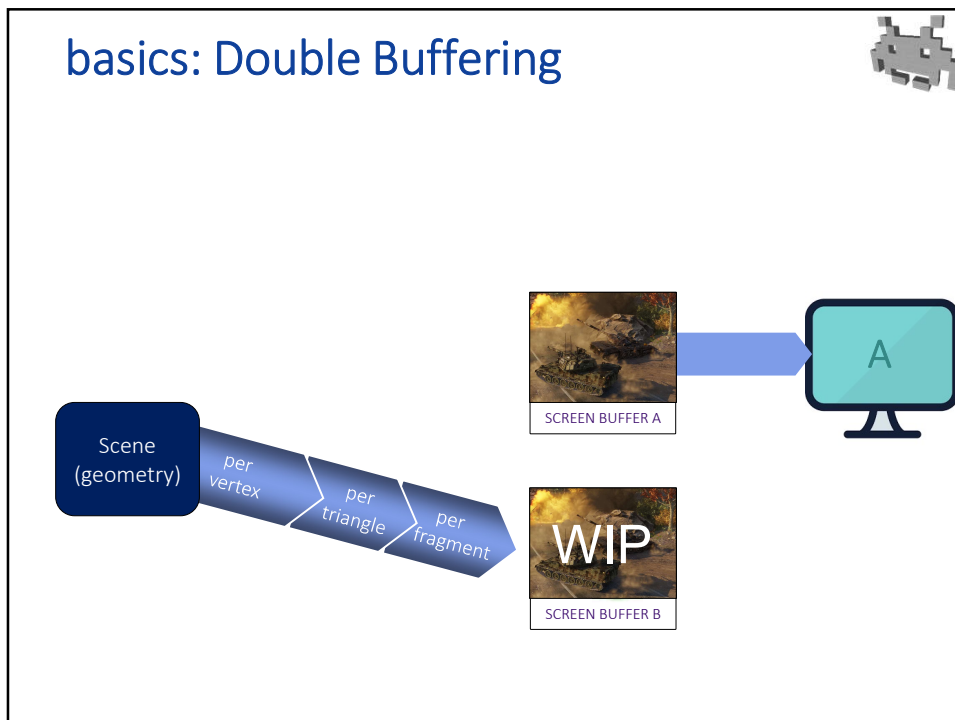
basics: Double Buffering

- To render a scene, all meshes are rendered succession
 - Filling the screen buffer
- Double-buffering is a basic technique to prevent any incomplete buffer to ever reach the screen
 - E.g., a rendering where some of the meshes is still not rendered
- How it works:
 - We have two RGB buffers: the front-buffer and the back-buffer
 - The **front buffer** shows the last complete rendering and is the one the screen shows
 - The **back buffer** is filled by the renderings, but it is not shown (it's yet another example of "off-screen buffer")
 - Screen Swap: When the back buffer is ready, the two buffer are swapped (instantaneously)
 - Info about variants: look up what "V-sync" means in 3D games settings
 - Observation: the depth-buffer is not doubled

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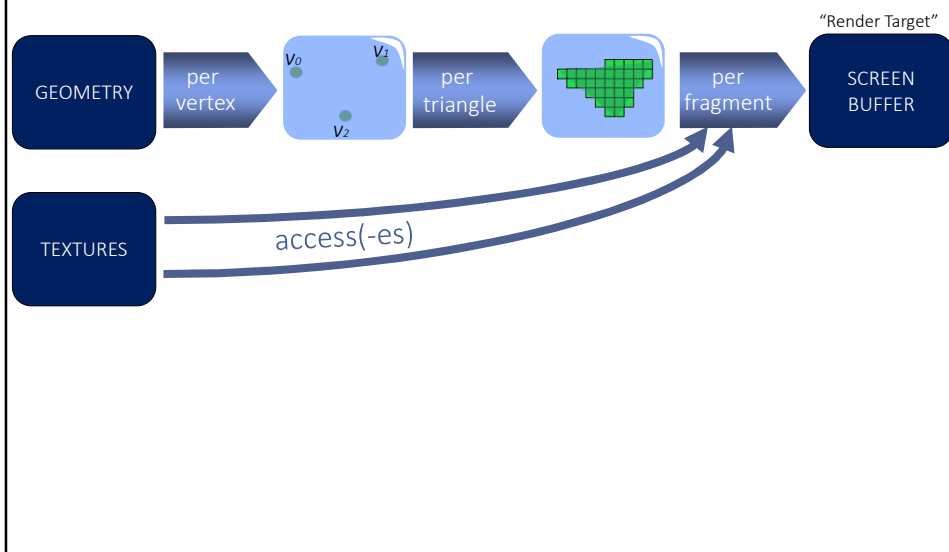
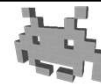
basics: Per-pixel lighting



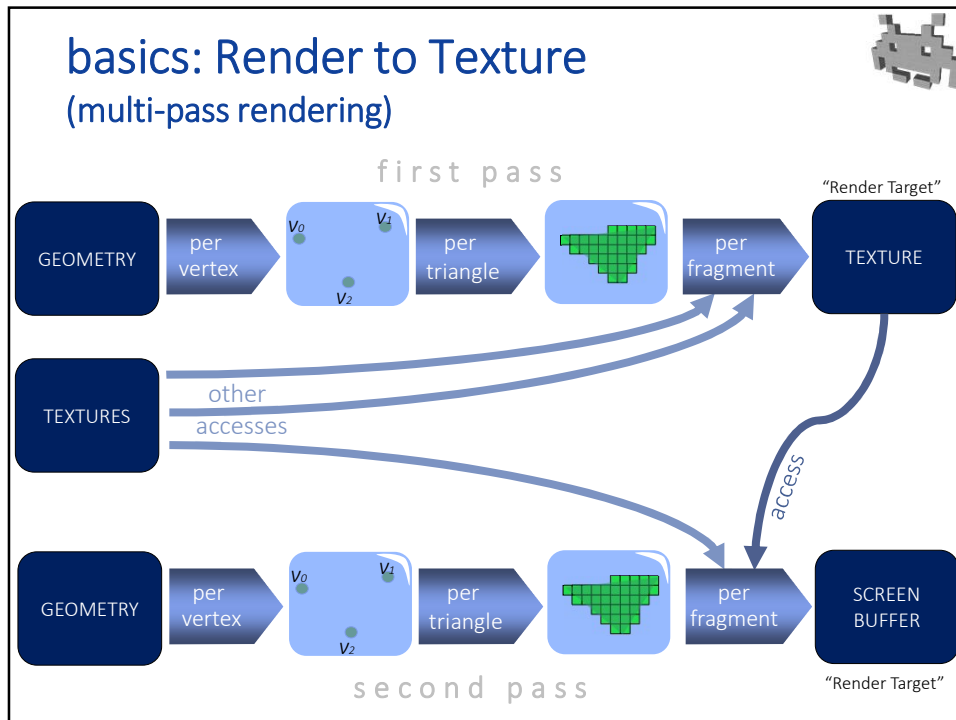
- Typically, lighting happens at the per fragment (per pixel) stage
 - the cheapest option, compute lighting per vertex, (and interpolate the resulting final RGB) saves computation but impacts quality (and disallows normal-maps and textures) ← formerly known as "Gouraud shading"
- Non uniform material parameters are
 - gathered from textures with **texture accesses**
 - or **interpolated** from per-vertex attributes (cheaper) ← heavily optimized, but still expensive
- Because lighting equations are now quite complex, this burdens the per-pixel stage considerably!
 - For this reason, games are often **fill-limited**

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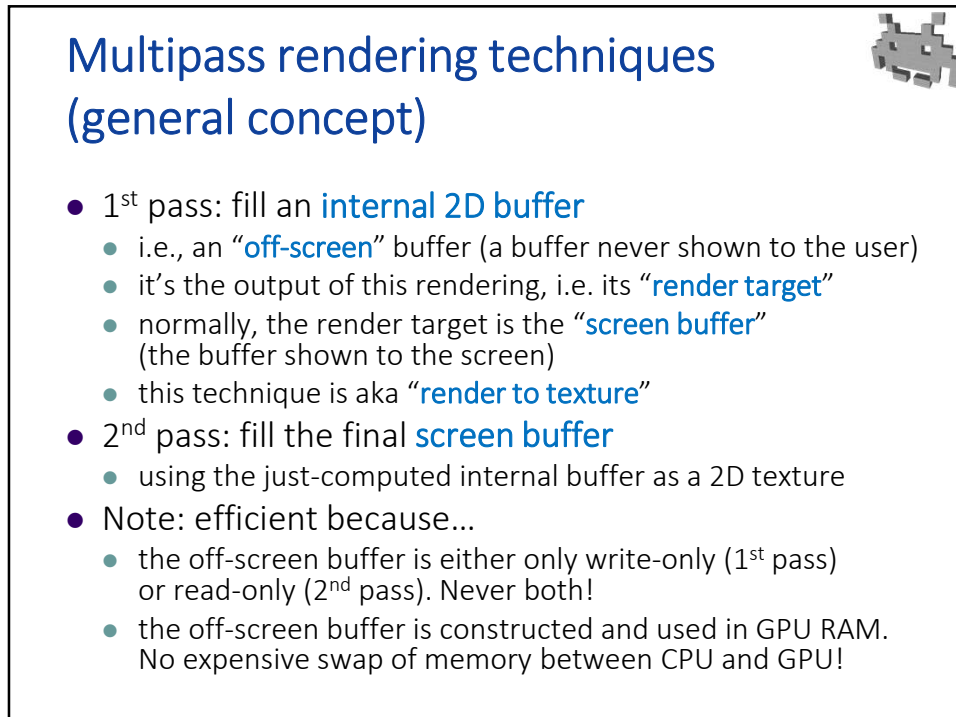
Texture access: it's in the per fragment process



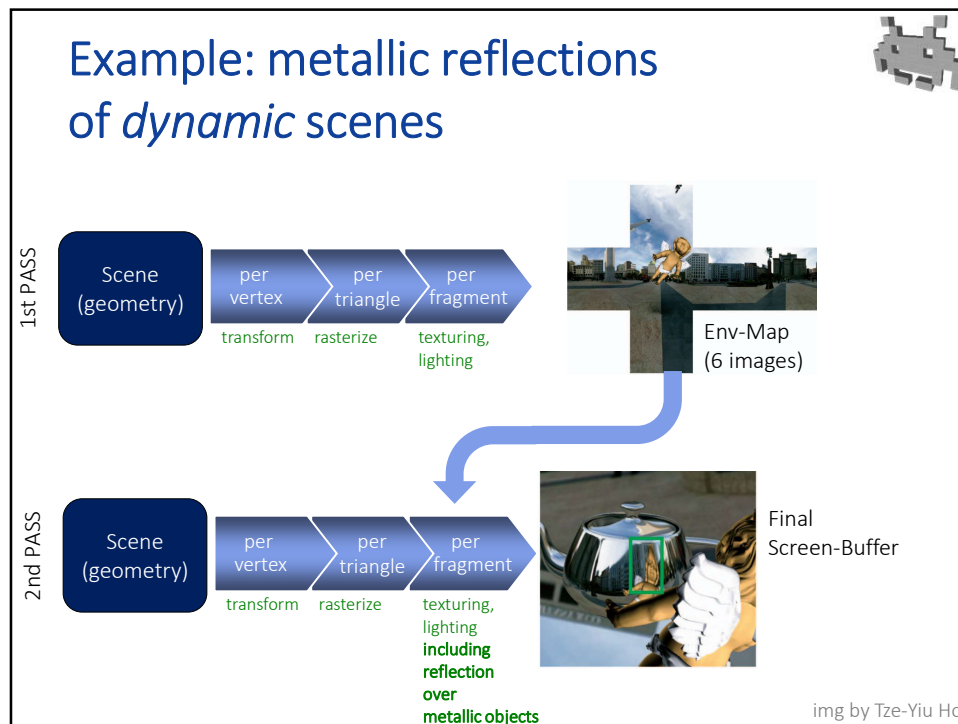
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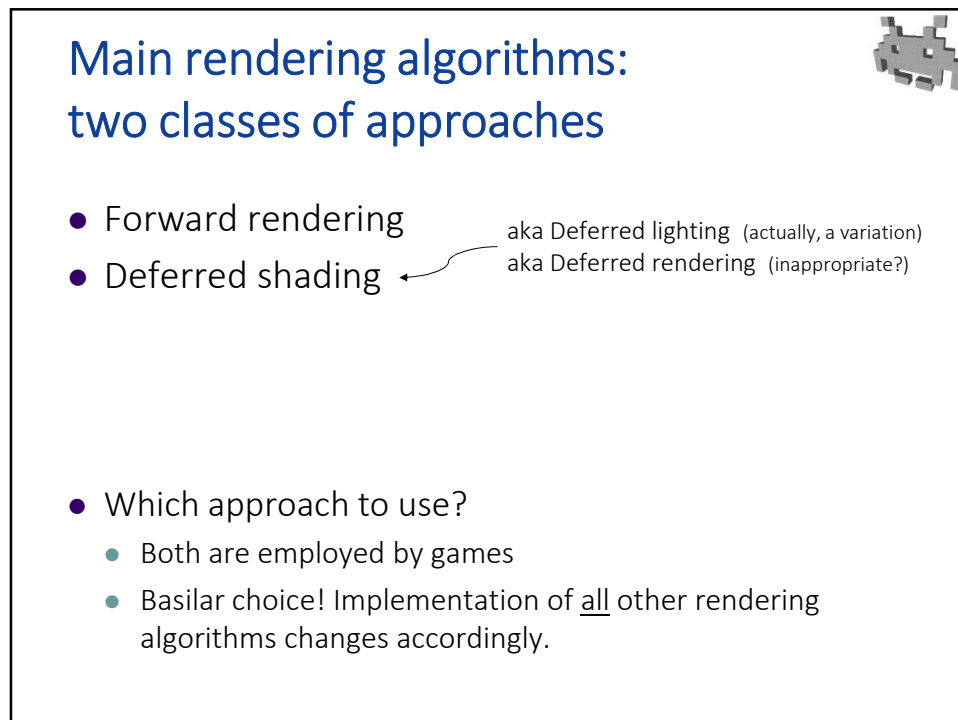
67



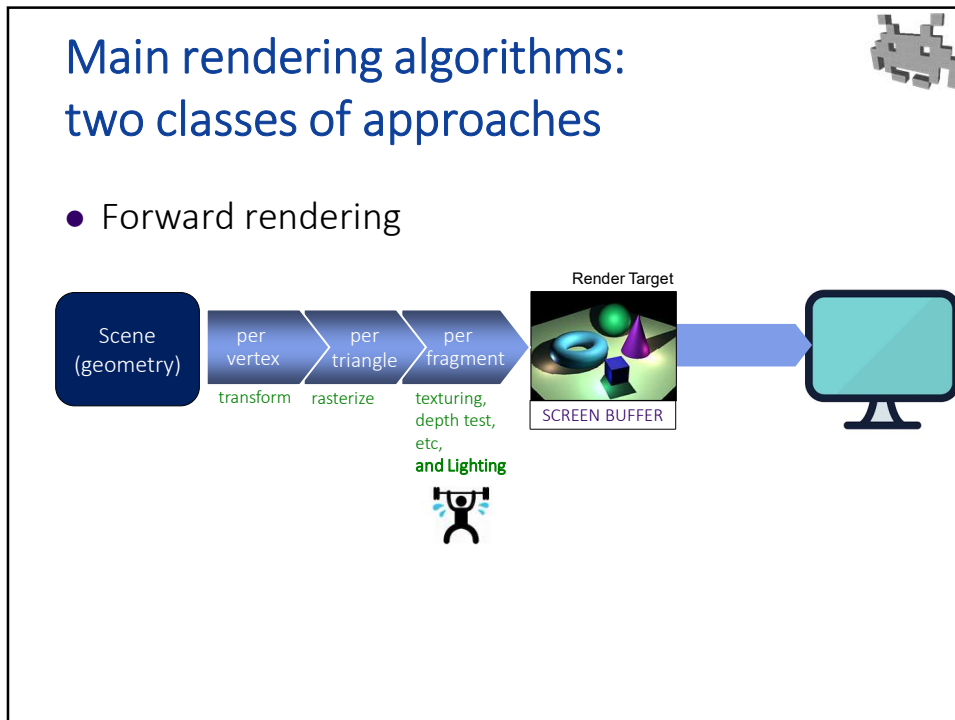
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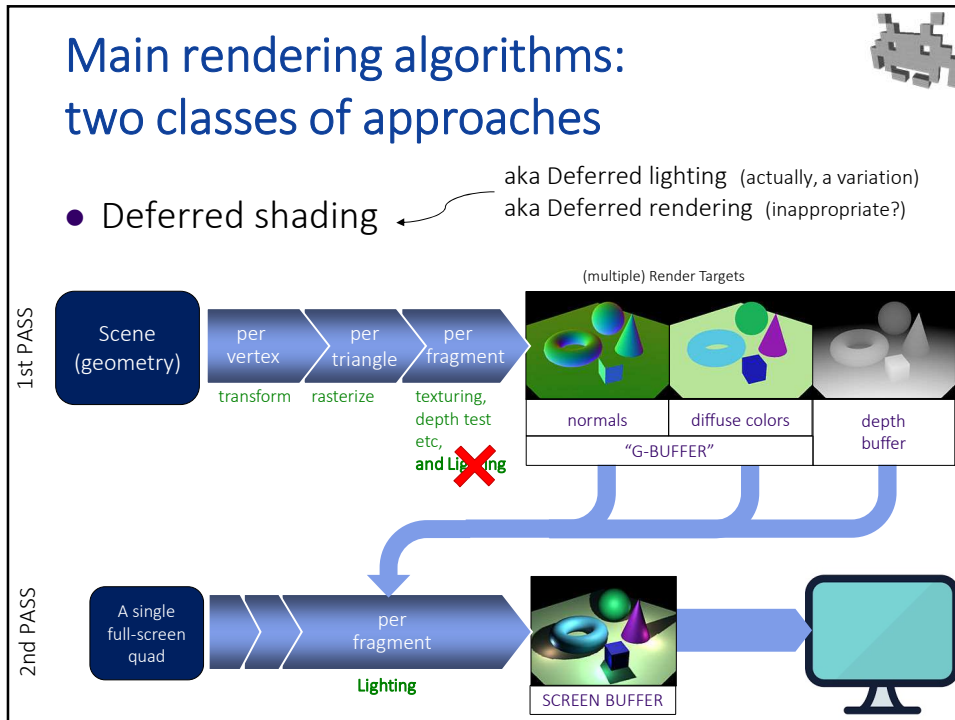
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Deferred shading



- Advantage:
 - lighting is computed only actually visible pixels
 - it's a huge saving if large **depth complexity** (aka overdraw) and/or **lighting complexity** – both common in 3D games
- Disadvantage:
 - needs a separate buffer for every material parameter (or, sometimes, a material **index**)
 - Normal buffer
 - Depth buffer
 - Base color buffer
- Limits the range of materials?
- Disadvantage: not good for semi-transparencies

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Ad-hoc rendering techniques popular in games: things we will see



- Shadowing
 - shadow mapping ← with **PCF**
 - Screen Space Ambient Occlusion ← **SSAO**
- Camera lens effects
 - Flares
 - limited Depth Of Field ← **DoF**
- Motion Blur
- High Dynamic Range ← **HDR**
- Non-Photorealistic Rendering ← **NPR**
 - e.g., cell shading:
 - 1. contours
 - 2. lighting quantization
- Texture-for-geometry
 - Bump-mapping
 - Parallax mapping

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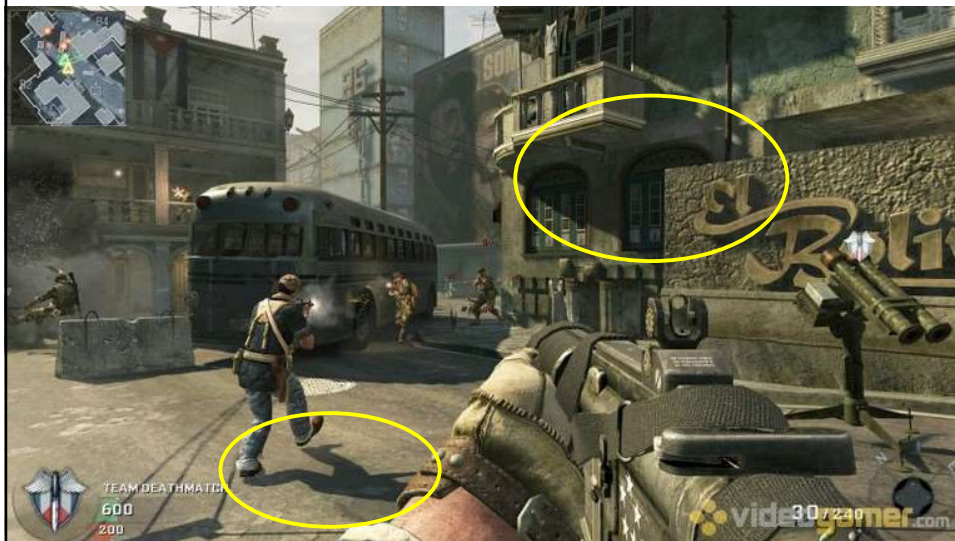
Screen-Space techniques (in general) (a class of multi-pass techniques)



- 1st pass:
 - Render the scene from the **same point of view** as the final scene
 - Produce: final color buffer, plus a z-buffer (and/or other auxiliary buffer)
- 2nd pass:
 - render just one single “full screen” rectangle
 - (it filling the entire screens with two triangles)
 - for each produced fragment: apply 2D effects to the buffer
- Notes:
 - Basically, we can apply image filters to the rendering.
 - Many of the techniques in the previous slides are like this

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Shadow mapping



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Shadow mapping



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Shadow-mapping in a nutshell (a multi-pass technique for shadows)

1st pass:

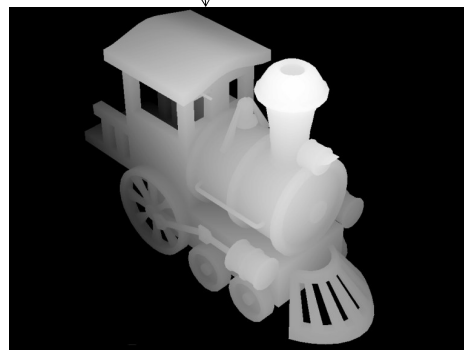
- camera in light position
- render all light blockers
- produce a depth buffer *only* (known as the **shadow map**)
- (repeat for each discrete light casting a shadow)

2nd pass:

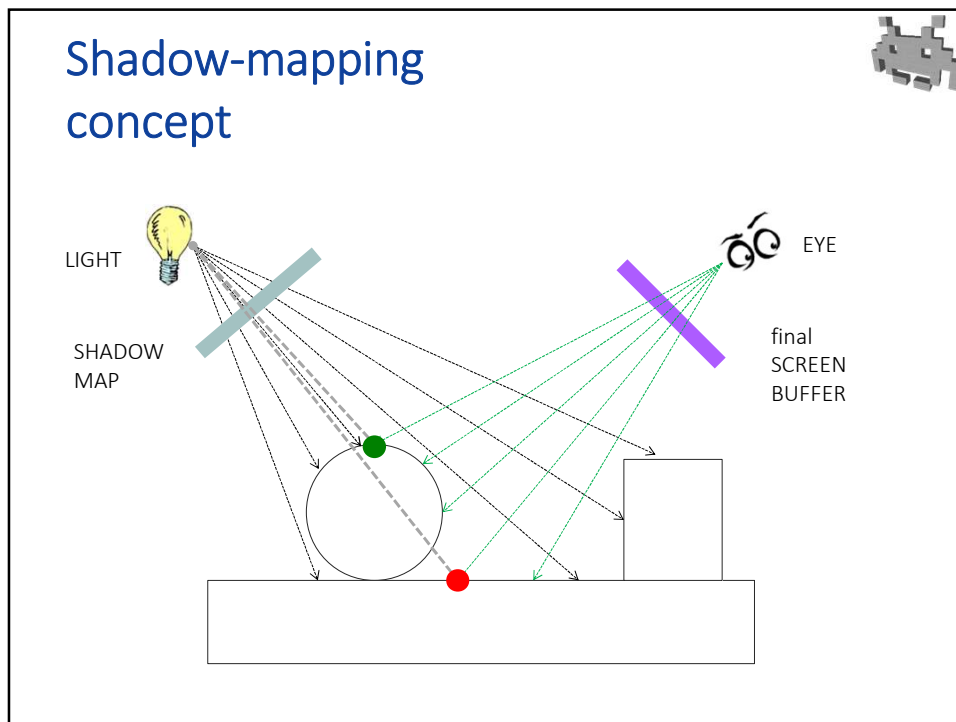
- camera in final position
- for each fragment, access the shadow-map, determine if that fragment is visible by light (or not)
- If not visible, negate contribution of that discrete light source

• Result:

- Blockers cast a shadow



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Shadow mapping: issues

- Rendering shadow-map:
 - Must be redone every time object move
 - can be baked once and for all, for static objects only
 - (jet another reason to label static objects!)
- Shadow-map resolution:
 - it matters! aliasing effects
 - remedies: PCF, multi-res shadow-map

optional topics (no exam)

The two screenshots show a stone platform in a game environment. The left image shows a shadow cast by the platform that has a very jagged, pixelated edge, which is an aliasing artifact. The right image shows the same scene but with a much smoother shadow edge, demonstrating the effect of a higher resolution shadow map or a technique like PCF.

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Shadow Mapping: effect of being in shadow

repeat for each light source

$$\begin{aligned}
 & \overbrace{\left(\hat{n} \cdot \hat{L} \right) \otimes \begin{pmatrix} d_R \\ d_G \\ d_B \end{pmatrix} \otimes \begin{pmatrix} L_R \\ L_G \\ L_B \end{pmatrix}}^{\text{diffuse term}} + \overbrace{\left(\hat{n} \cdot \hat{H} \right)^2 \otimes \begin{pmatrix} s_R \\ s_G \\ s_B \end{pmatrix} \otimes \begin{pmatrix} L_R \\ L_G \\ L_B \end{pmatrix}}^{\text{specular term}} + \underbrace{\begin{pmatrix} a_R \\ a_G \\ a_B \end{pmatrix} \otimes \begin{pmatrix} A_R \\ A_G \\ A_B \end{pmatrix}}_{\text{ambient term}} + \underbrace{\begin{pmatrix} e_R \\ e_G \\ e_B \end{pmatrix}}_{\text{emission term}}
 \end{aligned}$$

negated for that light source
(if with PCF: maybe only in part)

● material parameter
● light parameter
● geometry

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Shadow Mapping: effect of being in shadow

- Negates (zeroes) the light term of that (discrete) light-source
- Observe: the other light components are unaffected:
 - Other (non shadowed) lights
 - The ambient factor
 - Emission factor

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Screen Space AO (SSAO)



SSAO only

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Ambient occlusion (AO)

- **Cast shadows** (computed by **shadow-maps**) negate the light coming from discrete light sources
- “**Ambient occlusion**”, negates (occludes) the “**ambient**” component of lighting, instead
- Idea:
 - the AO is a factor (between 0 and 1) for each surface point
 - AO factor multiplies the ambient component for that point
 - Intuitively, for a point **p**, its AO factor is a measure of how much **p** is exposed in the open
 - **p** is well exposed: $AO \approx 1.0$
 - **p** is hidden, e.g. it is in the bottom of a crack: $AO \approx 0.0$
 - Exact definition - not in this course. But keep in mind:
 - (1) it is an approximation
 - (2) it is a purely geometrical computation

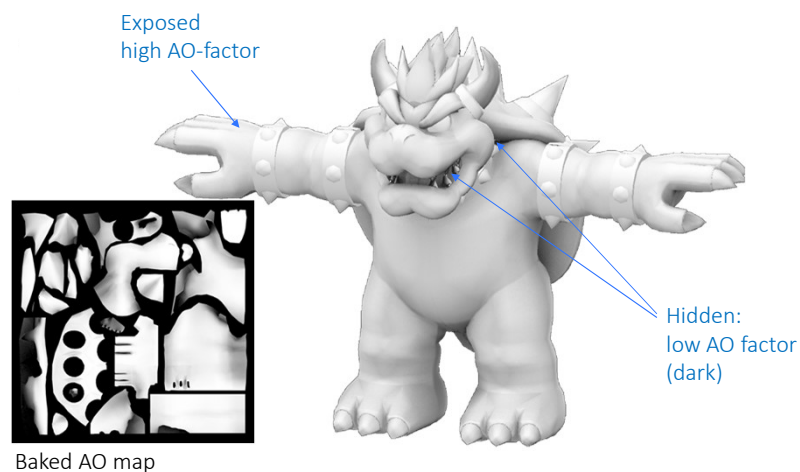
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Two ways to compute AO: OSAO versus SSAO

- Object Space Ambient Occlusion (OSAO)
 - Baked in preprocessing on each mesh
 - Stored as a per-vertex attribute OR a texture ("AO-map", or "light-map")
 - Pro: accurate & cheap (during rendering)
 - Con: static! Doesn't reflect current pos of the objects in the scene
- Screen Space Ambient Occlusion (SSAO)
 - Screen space technique
 - 1st pass: compute depth map (maybe normal too)
 - 2nd pass: compute AO map from the above (AO factor of each pixel, depends on neighboring depth values)
 - Final pass: use AO per-pixel from pass 2
 - Pro: dynamic! Reflect current position of objects in the scene
 - Con: less accurate
- Can be combined!

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Baking AO over a mesh (OSAO)



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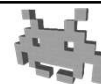
Screen Space AO in a nutshell



- 1st pass: standard rendering
 - produces: rgb image
 - produces: depth image
- 2nd pass: screen space technique
 - for each pixel, look at its depth VS depths of its neighbors:
 - Neighbors are in front?
 difficult to reach pixel: low AO factor (closer to 0)
 - neighbors are behind?
 pixel exposed to ambient light: high AO factor (closer to 1)

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Ambient occlusion: effects



repeat for each light source

$$\underbrace{\left(\hat{n} \cdot \hat{L} \right)}_{\text{diffuse term}} \otimes \begin{pmatrix} d_R \\ d_G \\ d_B \end{pmatrix} \otimes \begin{pmatrix} L_R \\ L_G \\ L_B \end{pmatrix} + \underbrace{\left(\hat{n} \cdot \hat{H} \right)^E}_{\text{specular term}} \otimes \begin{pmatrix} s_R \\ s_G \\ s_B \end{pmatrix} \otimes \begin{pmatrix} L_R \\ L_G \\ L_B \end{pmatrix} + \underbrace{\begin{pmatrix} a_R \\ a_G \\ a_B \end{pmatrix} \otimes \begin{pmatrix} A_R \\ A_G \\ A_B \end{pmatrix}}_{\text{ambient term}} + \underbrace{\begin{pmatrix} e_R \\ e_G \\ e_B \end{pmatrix}}_{\text{emission term}}$$

negates some % of this

material parameter

light parameter

geometry

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(limited) Depth of Field



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(limited) Depth of Field in a nutshell

- Screen space technique:
- 1st pass: standard rendering, producing
 - RGB image (kept off screen)
 - depth-buffer (as usual)
- 2nd pass:
 - pixel inside of focus range? Keep in focus
 - pixel outside of focus range? blur
 - Blur, way 1 = average with neighboring pixels
kernel size \approx amount of blur
 - Blur, way 2 = compute MIP-map of RGB image,
use lower MIP-map level with bilinear interpolation

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HDR - High Dynamic Range (limited Dynamic Range)



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HDR - High Dynamic Range in a nutshell



- Screen space technique:
- First pass: fill the off-screen buffer like a normal rendering, EXCEPT use lighting / materials value that are HDR
 - so, RGB of final pixel values not in $[0..1]$
 - e.g., sun emits light with RGB $[15.0, 15.0, 15.0]$: ←
 - >1 = “overexposed”!
i.e., “whiter than white”
(here: 15 times brighter than the maximal screen brightness)
- Second pass:
 - Make values >1 bleed over neighboring pixels
 - i.e.: overexposed pixels lighten neighbors pixels
 - Result: halo effect

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Motion Blur



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Non-PhotoRealistic Rendering (NPR)

- Any rendering technique not aimed at realism
- Instead, the objective can be:
 - imitating a given style (**imitative rendering**), such as:
 - cartoons (“toon shading”) ← most popular!
 - pen-and-ink drawings
 - pencil sketches
 - pixel art ← popular in nostalgic retro games (niche)
 - manga, comics, etc ← very common
 - pastels, oil paintings, crayons ...
 - clarity/readability (**illustrative rendering**)
 - usually not for games

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Toon shading / Cel Shading



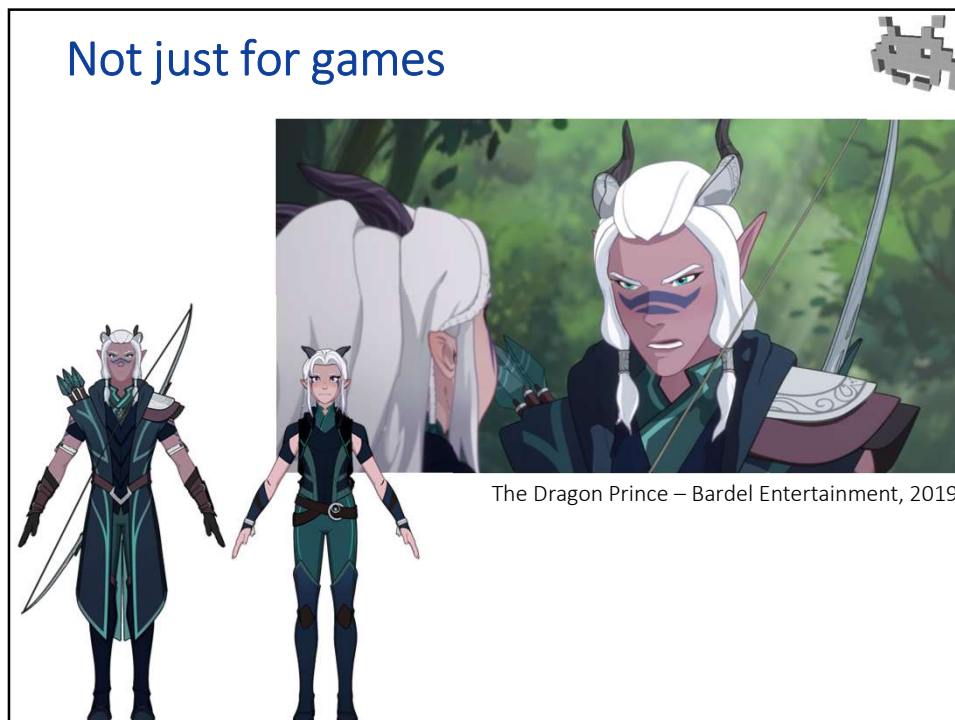
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Toon shading / Cel Shading



(tweaked) Team Fortress II – Steam

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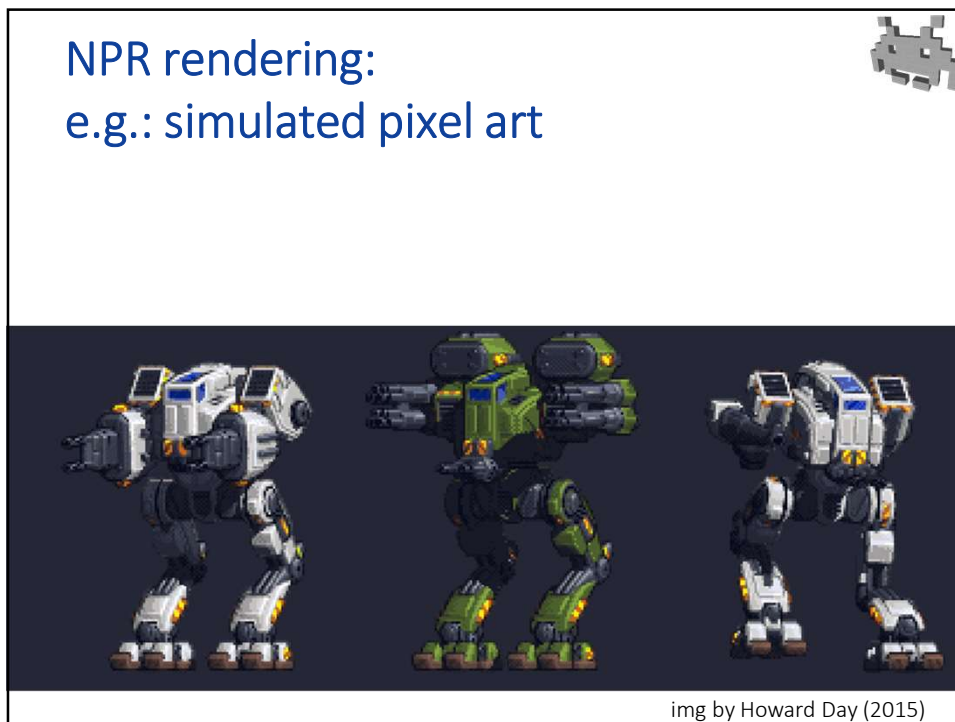


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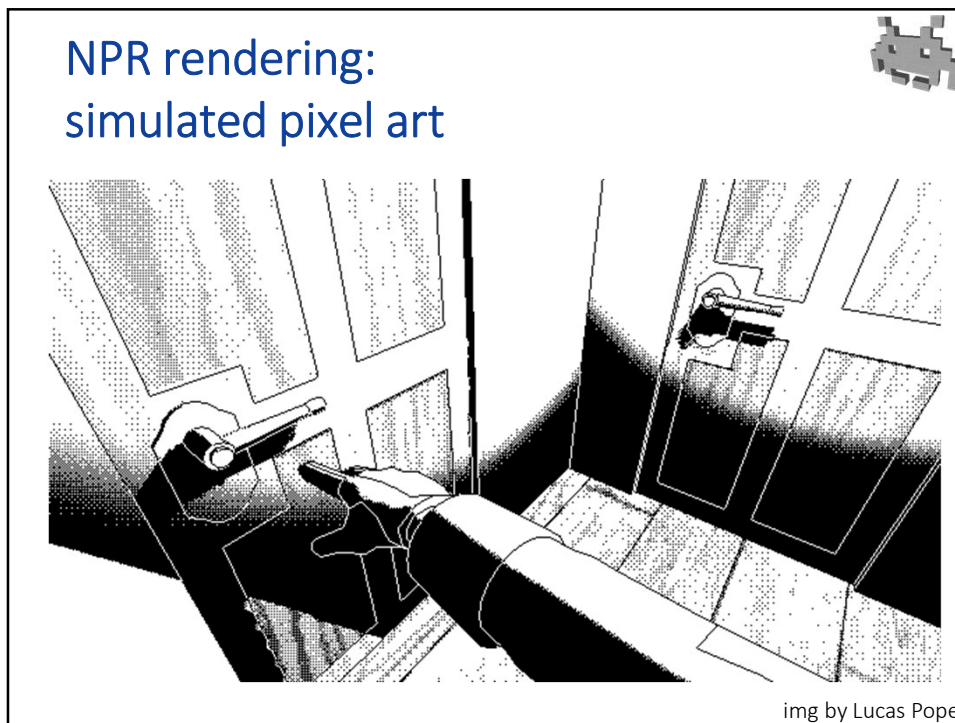
Toon shading / Cel Shading in a nutshell

- Simulating “toons” / hand drawn effect
- At its basics, a combination of two effects:
 - addition contour lines
 - lines appearing at discontinuities of:
 1. depth,
 2. normals,
 3. materials
 - quantized lighting:
 - e.g., 2 or 3 tones: light, medium, dark instead of continuous shades
 - a simple variation of lighting equation: quantize its result

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