

3D video games

Models for Games




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1

Course Plan



lec. 1: Introduction ●

lec. 2: Mathematics for 3D Games ●●●●●

lec. 3: Scene Graph ●

lec. 4: Game 3D Physics ●●●●+●●

lec. 5: Game Particle Systems ●

lec. 6: Game 3D Models ●●

lec. 7: Game Materials ●

lec. 9: Game Textures ●●

lec. 8: Game 3D Animations ●●●

lec. 10: 3D Audio for 3D Games ●

lec. 11: Networking for 3D Games ●

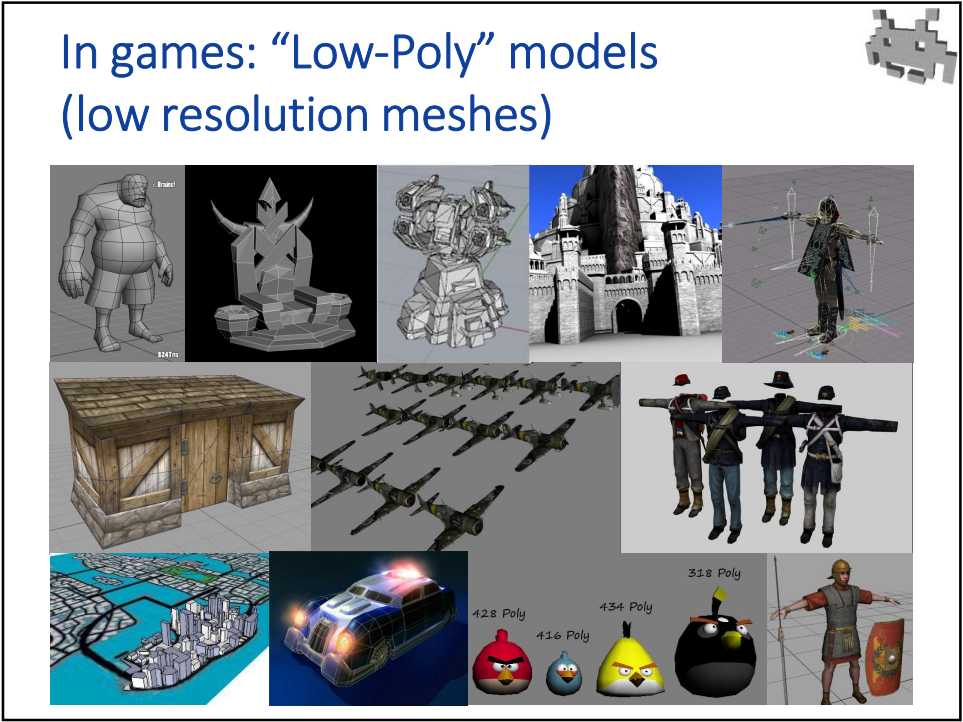
lec. 12: Artificial Intelligence for 3D Games ●

lec. 13: Rendering Techniques for 3D Games ●

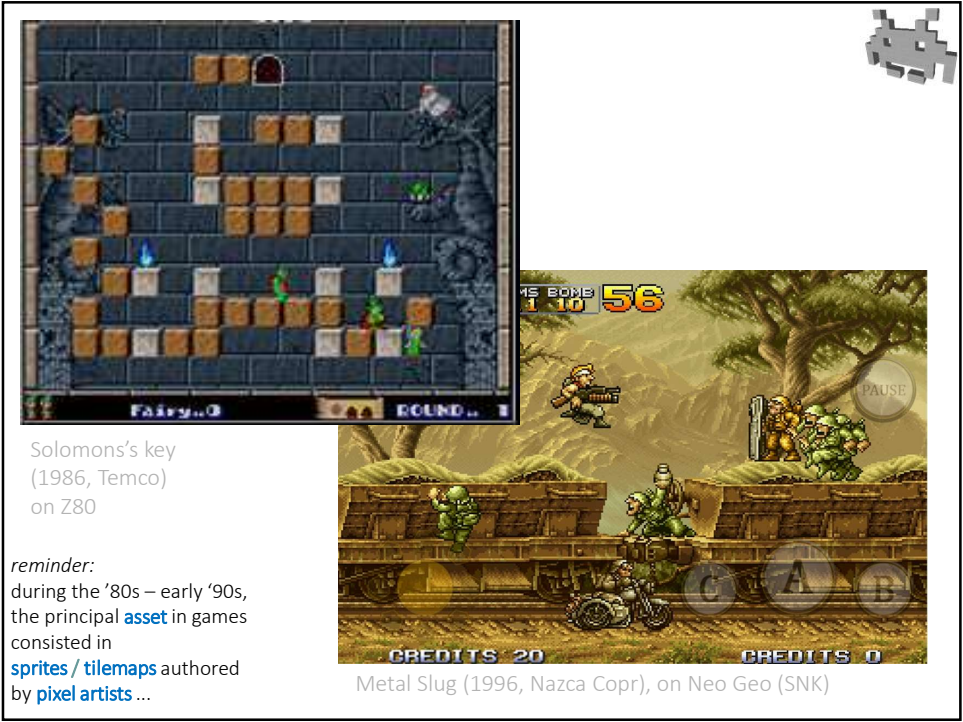
★

appearance

2



3



6

Triangle Meshes: the visual appearance of 3D objects



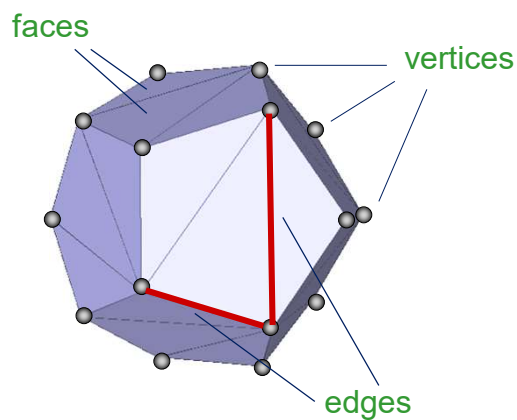
- Data structure for modelling 3D objects
 - GPU friendly
 - Resolution = number of faces
 - Resolution is (potentially) Adaptive (that is, more faces where needed)
- Used to model the **visual appearance** of 3D physical objects in the game
 - at least, the ones which can be represented by their surface
 - most solid objects (rigid or not)
- Mathematically: a piecewise linear approximation of the surface
 - a set of 3D samples, “vertices” connected by a set of triangular “faces” connected side to side by “edges”

7

Triangle Mesh (or simplicial mesh)



- A set of adjacent triangles



8

Mesh: data structure

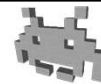


A mesh consists of

- **geometry**
 - The set of (x,y,z) positions of the vertices
 - It's a sampling of the surface
- **connectivity** (or **topology**)
 - The set of faces connecting the vertices
 - In a triangle mesh: faces are triangles (this is what the GPU is designed for!)
 - In a quad mesh: faces are quadrilateral
 - Quad dominant mesh: *most* faces are quadrilateral
 - Polygonal mesh: faces are polygons (general case)
- **attributes**
 - Data stored at vertices, such as: color, material, normal, ...

9

Mesh: geometry



- Set of vertices
 - A position vector (x,y,z) for every vertex
 - Coordinates, by definition, are given in Local space!

V1

V2

V3

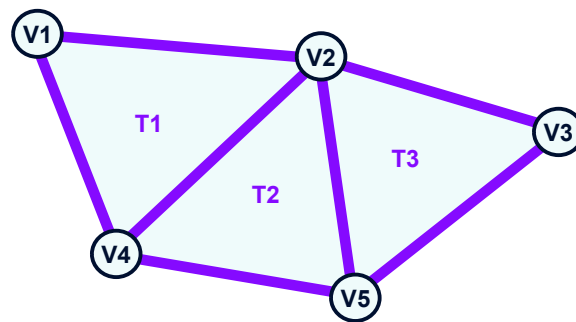
V4

V5

10

Mesh: connectivity (or topology)

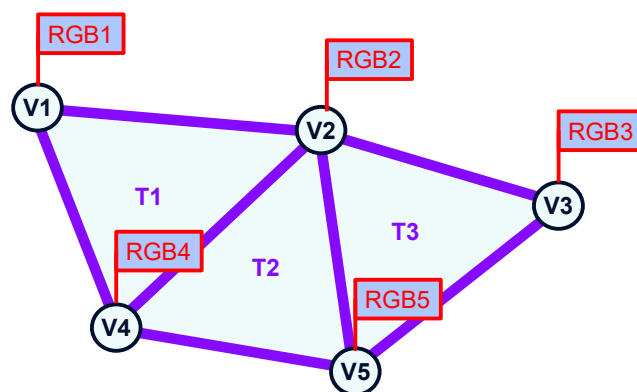
- Faces: triangles connecting vertices
 - More in general, polygons,
 - connecting triplet of *vertices*
 - just as, in a graph, *nodes* are connected by *edges*



11


Mesh: attributes

- Any quantity that varies over the surface
 - sampled at vertices, and interpolated inside triangles



12


Mesh as a data structure: indexed meshes



- array of vertices
 - Each vertex stored as
 - x,y,z position (aka the “geometry” of the mesh)
 - attributes: (all vertices, the same ones)
any data saved on the surface: e.g. color
- array of triangles
 - the “connectivity”
 - Each triangle stored as
 - triplet of **indices** (referring to a vertex in the array)

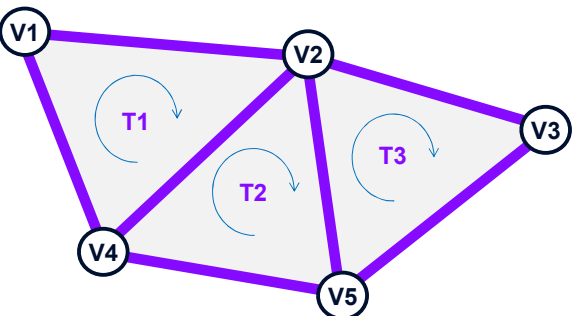

These two arrays can be seen as tables (buffers)

we can consider positions as attributes too



14

An indexed mesh in VRAM : two buffers



vert	X	Y	Z	R	G	B
V1	x1	y1	z1	r1	g1	b1
V2	x2	y2	z2	r2	g2	b2
V3	x3	y3	z3	r3	g3	b3
V4	x4	y4	z4	r4	g4	b4
V5	x5	y5	z5	r5	g5	b5

GEOMETRY + ATTRIBUTES

Tri:	Wedge 1:	Wedge 2:	Wedge 3:
T1	V4	V1	V2
T2	V4	V2	V5
T3	V5	V2	V3

CONNECTIVITY

15

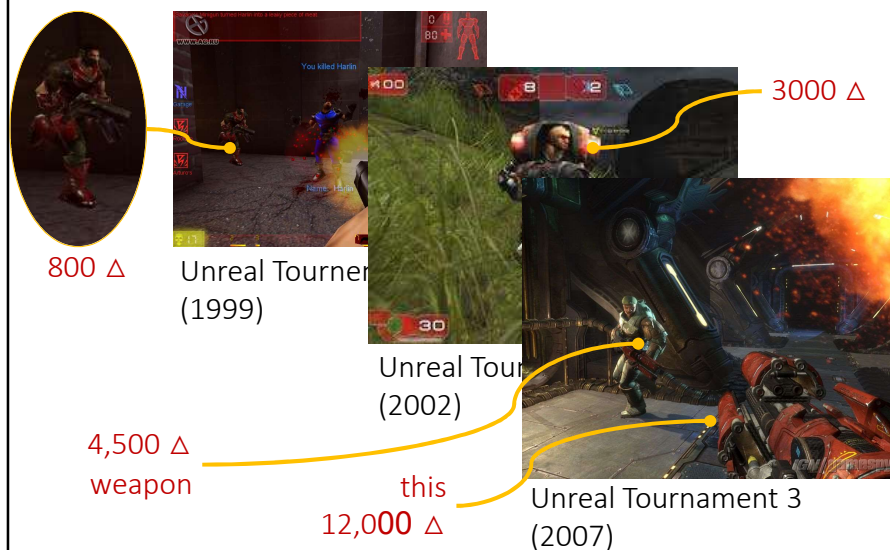
Mesh resolution



- Defined as the number of faces
 - or vertices, equivalent because typically $\#F \approx 2 \cdot \#V$
- Rendering time is linear with resolution
 - therefore, in games, resolution is kept small
 - aka. «low-poly» models
- Resolution can be adaptive:
 - denser vertices & smaller faces in certain parts
 - sparser vertices & larger faces in other parts
- Resolution of typical models increases with time
 - e.g. 1990s: $10^5 \Delta$ is hi-res
 - 2000s: $10^{10} \Delta$ is hi-res

16

Resolution increases over time



19



21

Mesh attributes: in general (this applies to any attribute)

- Attribute = any properties stored on the mesh, varying on the surface
 - Can consist of vectors, versors, or scalars
- It's stored at each vertex
 - Each vertex of a mesh = same collection of attributes
- It's (implicitly) interpolated inside the faces
 - Linear interpolation: uses barycentric coordinates (see next slides)
- Note: by construction, in indexed meshes attributes are C0 continuous across faces
 - but C1 discontinuous across faces
 - and C ∞ inside faces

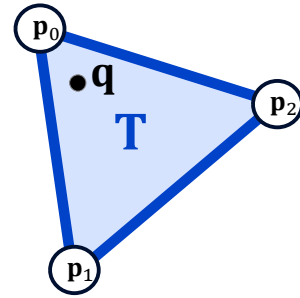
22

Interpolation of vertex attributes inside mesh triangles 1/2

- A triangle \mathbf{T} with vertices $\mathbf{p}_0, \mathbf{p}_1, \mathbf{p}_2$
- For every point \mathbf{q} in \mathbf{T} there are (unique!) k_0, k_1, k_2 with $k_0 + k_1 + k_2 = 1$ such that

$$\mathbf{q} = k_0 \mathbf{p}_0 + k_1 \mathbf{p}_1 + k_2 \mathbf{p}_2$$

- k_0, k_1, k_2 are called the **barycentric coordinates** of \mathbf{q} in \mathbf{T}



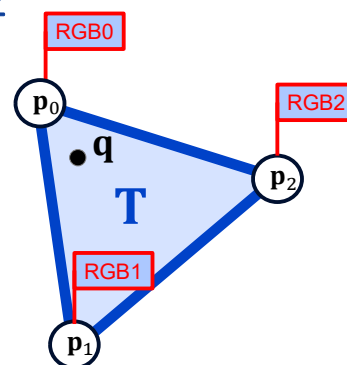
23

Interpolation of vertex attributes inside mesh triangles 1/2

- If we three attributes to the three vertices...
- a point \mathbf{q} in \mathbf{T} with barycentric coordinates k_0, k_1, k_2 is implicitly given the attribute value


$$k_0 \text{RGB0} + k_1 \text{RGB1} + k_2 \text{RGB2}$$

per vertex



24

Which mesh attributes are used in games: a summary (with spoilers)



in local space!

see lecture on textures (later)


see lecture on normal maps (later)

see lecture on animations (later)

- Position
(aka the “**geometry**” of the mesh)
- Normal
- Texture Coordinates
(aka the “**UV-mapping**” of the mesh)
- Tangent Direction
- Bone links
(aka the “**skinning**” of the mesh)
- Color

25

Mesh as buffer: a more realistic views



- Position
- Normal
- Color
- Texture Coordinate
- Tangent Direction
- Bone links

Tri:	W1:	W2:	W3:
T0			
T1			
T2			
T3			
T4			
T5			
T6			
T7			

CONNECTIVITY

vert	X	Y	Z	Nx	Ny	Nz	R	G	B	A	U	V	Tx	Ty	Tz	Bx	By	Bz
V0																		
V1																		
V2																		
V3																		
V4																		

GEOMETRY + ATTRIBUTES

Ints (with some # of bits)

Floating points (with a given precision)

27

Mesh attributes: colors



- In games, colors on 3D models are usually determined by textures (not by mesh colors)
 - reason: more detailed signals can be stored
- Per vertex colors can be used...
 - To cheaply add variations models
 - Red guards, blue guards
 - To **bake** lighting
 - e.g. baked per-vertex ambient occlusion see rendering later
 - To **dynamically** recolor mesh parts
 - e.g. redden the tip of a sword which is blood soaked
 - e.g. accumulate dirty
 - ...and more

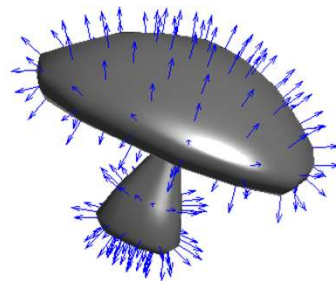
SEE MATERIALS LATER

28

Mesh attributes: normals



- A versor
- Representing the surface orientation
- Main use: lighting computation
- Can be computed automatically from geometry...
- But it is a part of the mesh assets:
 - the artist is in control of which edges are **soft** and which are **hard**



29

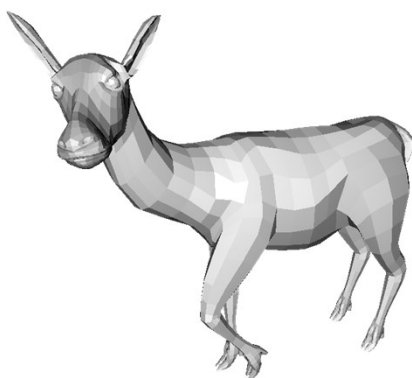
Mesh attributes: normals



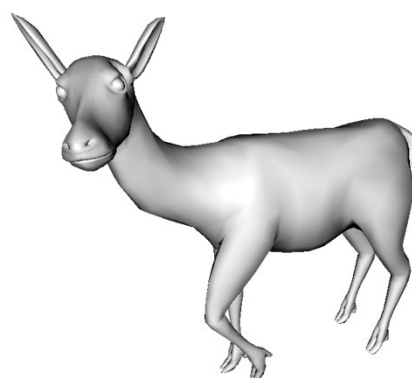
- Technically, mesh faces are *flat*
 - the normal is constant over a face
 - the normal is discontinuous across faces (each mesh edge is “sharp”)
- Usually, that’s not the surface we intend to represent
 - The flatness is just an artifact (a defect) of the mesh discretization
- By using a *continuously varying* normal (the per-vertex normal interpolated inside faces), the rendered images gives the illusion of a smooth, curved surface
 - which is (usually) what we want to represent
- But if we want, can we still represent “hard” (sharp) edges
 - With vertex seams: see below

30

Mesh attributes: normals



if «real» normals
where used
(«flat shading»)



Using interpolated
per vertex normals
(smooth shading)

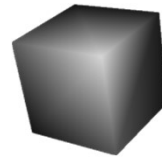
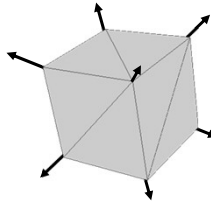
Note: normals are made visible to our eyes due to lighting
(computation of how light reacts with the surface)

31

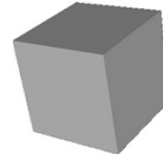
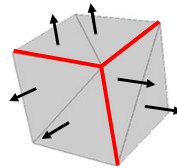
Hard edges (aka sharp edges) (aka “creases”)

- Edges where the normal is **not continuous**.

Soft edges:



Red edges
are hard



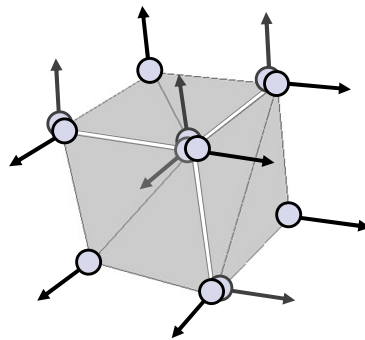
- How to encode (Co) a **discontinuity** in any attributes?

32

answer:

Vertex seams

- Vertex seam = two coinciding vertices. in xyz
 - different attributes assigned to each copy



33

Vertex seams

- A way to encode any attribute discontinuity
- Price to be paid:
a little bit of data replication...

	X	Y	Z	Nx	Ny	Nz
V0	p_x0	p_y0	p_z0	n_x0	n_y0	n_z0
V1	p_x1	p_y1	p_z1	n_x1	n_y1	n_z1
V2	p_x2	p_y2	p_z2	n_x2	n_y2	n_z2
V3	same	same	same	n_x3	n_y3	n_z3
V4	p_x3	p_y3	p_z3	n_x4	n_y4	n_z4
V5	same	same	same	n_x5	n_y5	n_z5
V6	p_x4	p_y4	p_z4	n_x6	n_y6	n_z6

GEOMETRY + ATTRIBUTES

Tri:	Wedge 1:	Wedge 2:	Wedge 3:
T0	0	1	4
T1	4	2	0
T2	5	3	6

CONNECTIVITY

34

Rendering of a Mesh in a nutshell

Load...

- get required data ready on GPU RAM
 - Geometry + Attributes buffer(s)
 - Connectivity buffer
 - Textures
 - Shaders
 - Parameters / Settings

...and Fire!

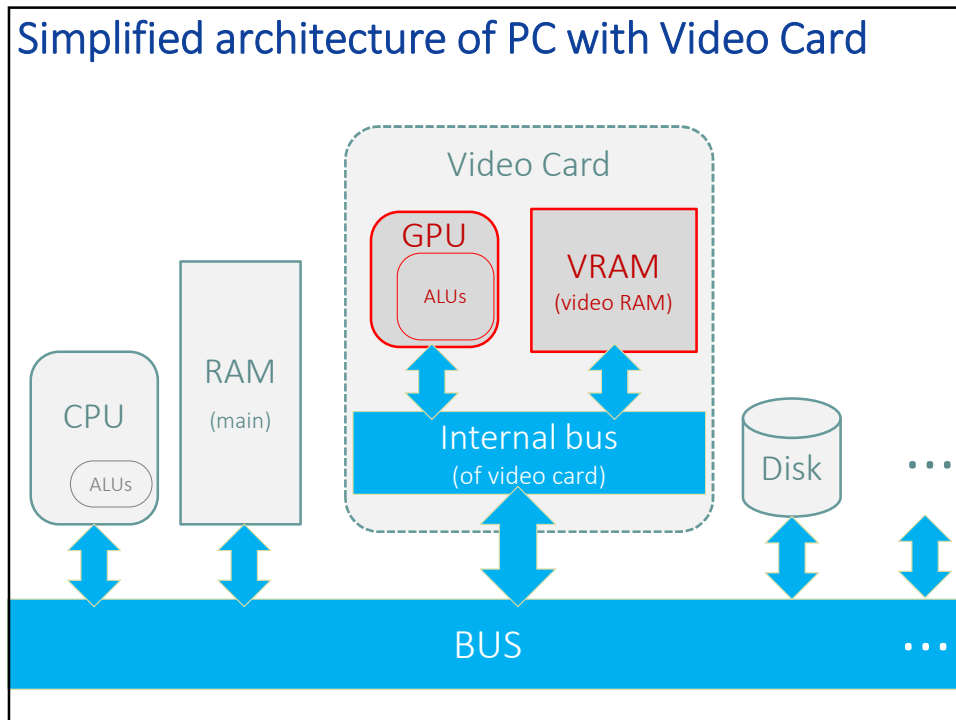
- send the “Draw-call” to the GPU
- using an API

35

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14



36

Rendering of a Mesh in a nutshell



Might change in the future?

- The algorithm to render a mesh (in games) is based on **rasterization**
 - It is outside the scope of this course. See CG course.
 - In brief, three phases in cascade:
 - each vertex** is projected on screen (“transform”), (find where the vertex will be seen on the screen)
 - then **each triangle** is rasterized (converted into pixels)
 - then **each pixel** is processed (find the final color)
- For our purposes, rendering a mesh means just: load all required data on the card on the GPU and send the command to render it (the “**draw call**”)
 - data includes the mesh itself (the two tables)
 - plus the current transformations (from local space to view space)
 - plus data describing the view: the “**material**”, including textures

PER VERTEX PHASE

PER TRIANGLE PHASE

PER PIXEL PHASE

37

Rendering of a Mesh in a nutshell

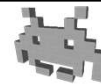


Exception:
semi-transparent
“see through”
objects

- A few things to know:
 - It is a strongly parallel task (all vertices, all triangles, all pixels can be processed in parallel)
 - The entire procedure is implemented in the GPU
 - It's **order-independent**: we can draw mesh in any order we like. The final result is the same
 - Time cost:
 $O(\text{number of vertices}) = O(\text{number of faces})$
but also, $O(\text{number of covered pixels})$ --- so the *slowest* of the two
 - The rendering procedure includes: animations (see later), lighting
- Because it's GPU-implemented, many things are **hard-wired**
 - The data structures: indexed meshes (rarely: a triangle soup instead)
 - (Note: only triangle-shaped faces can be rendered – not quads/etc)
 - The interpolation of attributes inside faces
- There's a bit of customizability because GPU can be programmed
 - Both the per-vertex phase (projection) and the per-pixel phase (lighting)
 - “Shader” = custom program

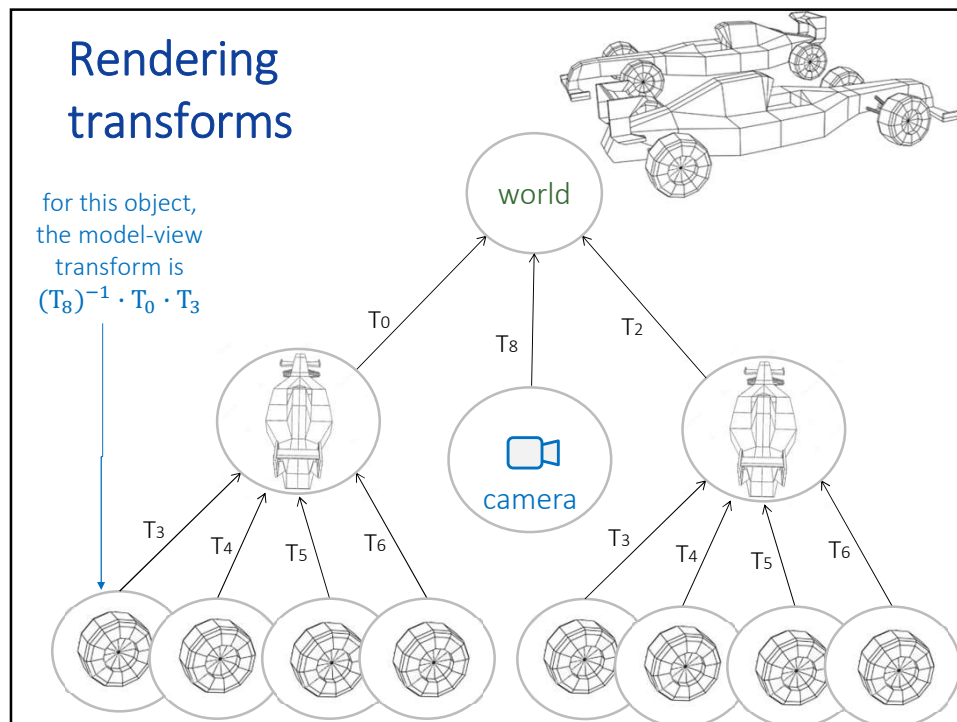
38

Rendering & Scene graph



- Rendering APIs encode transforms as a 4x4 matrix
 - reason: it is a more flexible, can also express perspective transforms
- To render an object:
 - Combine its Transforms from Object-space to Camera-space (“model-view transform” – in CG terminology)
 - Convert it into a 4x4 matrix
 - Use it during the rendering of the object
 - Note: from world to camera (“view matrix”) can be computed and used for all objects
- The model-view matrix is applied to each vertex
 - In the per-vertex processing
 - Combined with the “projection matrix” (from camera space to screen space) is called “model-view-projection” matrix)

39



40

Rendering order of the meshes - notes

(and particle effects too)

- Idea 1: depth-first visit of the scene graph
 - Advantage: incremental update of the global transform (used by rendering)
 - Cumulate local transform when going down, popping or cumulate inverse when going back up
 - Not a big advantage, after all – popular in CG, not much used in games
- Idea 2: render meshes according to the material they use: “load a material, then render all meshes that use that material”
 - In the example above: render all 8 wheels consecutively
 - Advantage: consistent rendering state (material = state of the renderer)
 - Remember: all data needed by the rendering must reside in GPU ram
 - Very popular method
- Idea 3: sort meshes front-to-back (Z-order in camera space)
 - Render meshes from the back
 - Correct order is needed of semitransparent objects
 - Problem: expensive to sort – not much used
 - Instead, the correct order of semi-transparent objects tweaked with tricks (postponing/preponing the rendering for certain materials – “render order”)

Known as
“painter’s algorithm”

42