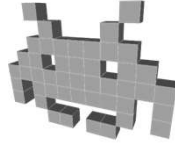

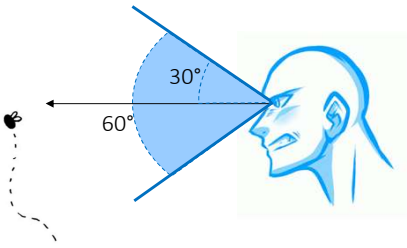


3D videogames

Points, Vectors, Versors: mini task and exercises




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Points, Vectors, Versors: mini task and exercises



- The following exercises (done in the classroom) use the vector
 - In some of them, the solution is given in full
 - In other, only a trace of the solution is given
- General schema for solutions:
 - Identify input and output (and it's type)
 - Write the equations driven by the intuitive/spatial understanding of the operations,
 - manipulate the equations according to the rules, extract the solution

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Points, Vectors, Versors: mini task and exercises



- Try to write pseudo-code that solves the proposed problems, using
 - An existing library (GLM, Unity, Unreal) GLSL..
 - Your own hand-made library for points/vectors/versor

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Point to point distance



“When the player in position \mathbf{p} is closer than k to a powerup in pos \mathbf{q} , then the powerup is collected”

- Data: \mathbf{p}, \mathbf{q} points, k versor
- Test: $\|\mathbf{p} - \mathbf{q}\| < k$
- Optimizing: $\|\mathbf{p} - \mathbf{q}\|^2 < k^2$
- Pseudo-code example:

```
vec3 p, q;  
scalar k;  
if ( dot(p-q, p-q) < k*k ) then /*collect*/
```

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Orthonormal base completion

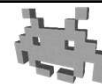


“I have a only two axes \hat{x} and \hat{y} of an orthonormal bases, how do I find the third vector \hat{z} ?”

- Data: \hat{x} , \hat{y} versors
- Hypotheses: \hat{x} and \hat{y} are already orthogonal
- Variant: \hat{y} is not exactly orthogonal to \hat{x} , but I want to change it the least to make it orthogonal (\hat{x} is to be kept constant)
(see next problem)

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Vector orthogonalization



“Find a versor \hat{u}' that is ortogonal to a given \hat{n} such that it is as similar as possible to a given versor \hat{u} ”

Solution: $\hat{u}' = \hat{n} \times \hat{u} \times \hat{n}$

```
vec3 n,u;  
u = cross( cross( n , v ) , n );
```

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Ray-sphere intersection

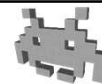


“I shoot a laser from \mathbf{p} to direction $\hat{\mathbf{d}}$. Do I hit a sphere in position \mathbf{q} of radius r ? Where?”

- Data: \mathbf{p}, \mathbf{q} points, r scalar, $\hat{\mathbf{d}}$ versor
- Trace:
 - Hit-point is \mathbf{s} on laser ray:
 $\mathbf{s} = \mathbf{p} + k \vec{\mathbf{v}}$, for some unknown scalar $k \geq 0$
 - Hit-point is \mathbf{s} on sphere:
 $\|\mathbf{q} - \mathbf{s}\| = r \iff (\mathbf{q} - \mathbf{s}) \cdot (\mathbf{q} - \mathbf{s}) = r^2$
 - Combine the two equations (substitute \mathbf{s} in second), solve for k (it's a 2nd degree equation), test that k exists and that it is >0

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Shooting a walking target (with a finite speed bullet) 1/2

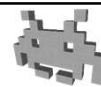


“I shoot a bullet from \mathbf{p} with velocity $\vec{\mathbf{v}}$. At which time the bullet will be the closest to a target currently in position \mathbf{q} and moving with velocity $\vec{\mathbf{w}}$? Where will bullet and target be, at that point?”

- Data: \mathbf{p}, \mathbf{q} points, $\vec{\mathbf{v}}$ and $\vec{\mathbf{w}}$ vectors
- Hypothesis: nothing accelerates (everything keeps moving at a constant speed)

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Shooting a walking target (with a finite speed bullet) 2/2



Trace

- Position of bullet at time t : $\mathbf{p} + t \vec{\mathbf{v}}$
- Position of target at time t : $\mathbf{q} + t \vec{\mathbf{w}}$
- Squared distance between the two at time t :

$$\begin{aligned} & \| (\mathbf{p} + t \vec{\mathbf{v}}) - (\mathbf{q} + t \vec{\mathbf{w}}) \|^2 \\ & = \\ & \| (\mathbf{p} - \mathbf{q}) + t (\vec{\mathbf{v}} - \vec{\mathbf{w}}) \|^2 \end{aligned}$$

- Work on formulas, derive for t , equate derivative to 0, extract t

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Ray-Plane intersection



“I shoot a laser from \mathbf{p} in direction $\hat{\mathbf{d}}$ toward a plane which contains points \mathbf{a} \mathbf{b} \mathbf{c} . Which point \mathbf{q} do I hit?”

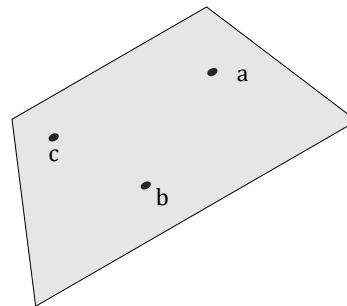
- Hypotheses: \mathbf{a} \mathbf{b} \mathbf{c} are not colinear (not on a line)
- Trace:
 - Find vector $\vec{\mathbf{n}}$ orthogonal to plane, use cross product (magnitude and verse are not important)
 - Define \mathbf{q} as point on the laser (see Ray-Sphere inters.)
 - Define \mathbf{q} as a point on the plane (hint: the vector connecting it to any other point on the plane is orthogonal to $\vec{\mathbf{n}}$)
 - Combine the two equations into one
 - Wxtract the incognita

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Sub problem: surface normal

“I have three points on a plane: find the normal \hat{n} of this plane (a versor)”

- Trace:
find any two
different vectors
on (i.e. parallel to)
the plane...



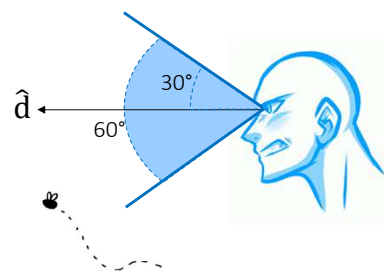
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Vision cones

“A guard has eyes in position q and looks in direction \hat{d} . Does it spot a fly in position p , if his cone of vision is 60° wide?”

- Hypotheses: no occlusions

- Trace:
 - For angles α, β in $0..90^\circ$: $\alpha < \beta \leftrightarrow \cos(\alpha) > \cos(\beta)$
 - Find cosine of angle between view direction and the vector connecting q to p
 - Determine if this cosine is $> \cos(60^\circ/2)$



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