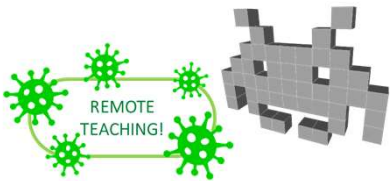
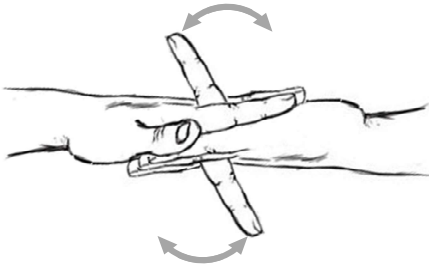


3D VideoGames
Unimi
Animations in games

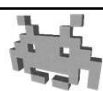


Marco Tarini



1

Course Plan



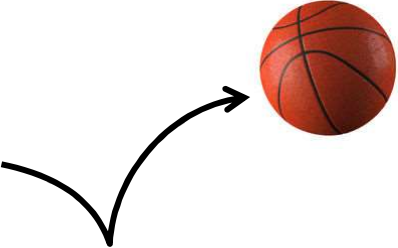
- lec. 1: **Introduction** ●
- lec. 2: **Mathematics** for 3D Games ●●●●●
- lec. 3: **Scene Graph** ●
- lec. 4: Game 3D Physics ●●● + ●●●
- lec. 5: Game Particle Systems ▶
- lec. 6: Game 3D Models ●◀
- lec. 7: Game Textures ▶●●
- lec. 8: Game 3D Animations ▶●●
- lec. 9: Game 3D Audio ●
- lec. 10: **Networking** for 3D Games ●
- lec. 11: **Artificial Intelligence** for 3D Games ●
- lec. 12: Game 3D Rendering Techniques ●●

2

Types of animations in games

1. of rigid objects

- animate scene transformations




(6 DoF per object)

3

Types of animations in games

1. of rigid objects

- or objects made of rigid sub-parts

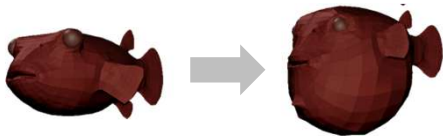




4

Types of animations in games

2. Free-Form deformations

- generic transformations of the object







5




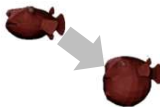
Types of animations in games

3. of articulated models


- internal skeleton
- most virtual characters!
- "skinning"



6

Types of animation and DoF (per keyframe)		DoF = Degrees of Freedom
<p>Rigid</p> 	<p>6 DoF per object (or, e.g., 9, with anisotropic scaling)</p>	
<p>Articulated</p> 	<p>~50-100 DoF per object (e.g. 3 DoF per joint x 25 joints)</p>	
<p>Free form</p> 	<p>300-10.000 DoF per object (e.g. 3 per-vertex)</p>	

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Animations in games		
<p>← Authored</p> <ul style="list-style-type: none">● Assets!● Control: easy. full control by artists (e.g. for dramatic fx)● Realism: hard it's up to the artist skill● Flexibility: little Doesn't adapt to env.● (consumes RAM)	<p>→ Procedural</p> <ul style="list-style-type: none">● Physic engine● Control: hard● Realism: easy built-in physical laws● Flexibility: great Adapts to env. / context● (consumes GPU)	

8

A digression on terminology



- depending on the context, the opposite of “**procedural**”, can be...
 - **baked** :
‘pre-cooked’, ‘frozen’ into an asset,
(when something was produced procedurally)
 - **asset** :
stored as an asset (irrespective of origin),
that is, read from the disk (or streamed from web)
 - **scripted** :
stored as a (*simple!*) script
but, the procedure to create something can well be a script!
e.g. “this *script procedurally generates* a level”
 - **authored / manually designed / edited** :
made by a digital artist (as opposed to, by a program)
 - **(fully) simulated** :
the output of a (*complex!*) simulation

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Summary: Types of authored animations



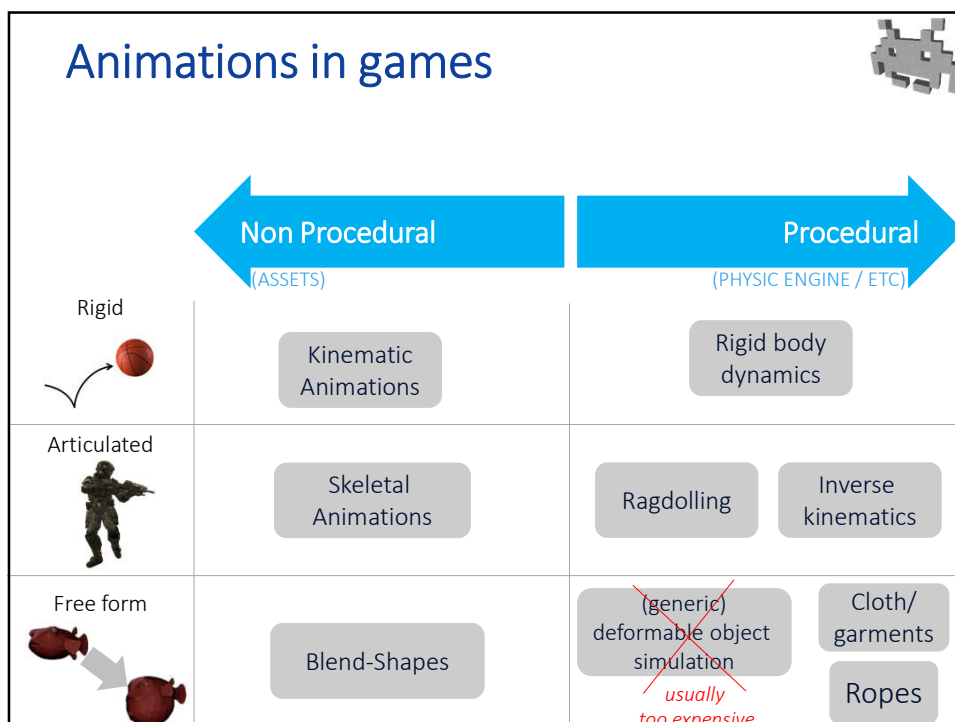
- of objects made of rigid subparts
 - including joints: robots, cars...
 - → “**forward kinematics animations**”
(dynamic changes of modelling transform)
- of deformable articulated objects
 - with some internal skeleton
 - e.g: most virtual characters:
humans / animals / monsters / anything in between
 - → “**skinning**” / “**rigging**”
- of generic deformable objects
 - e.g. faces, an umbrella, stuff with membrane...
 - “**per-vertex animations**” / “**blend shapes**” / “**morph targets**”

10

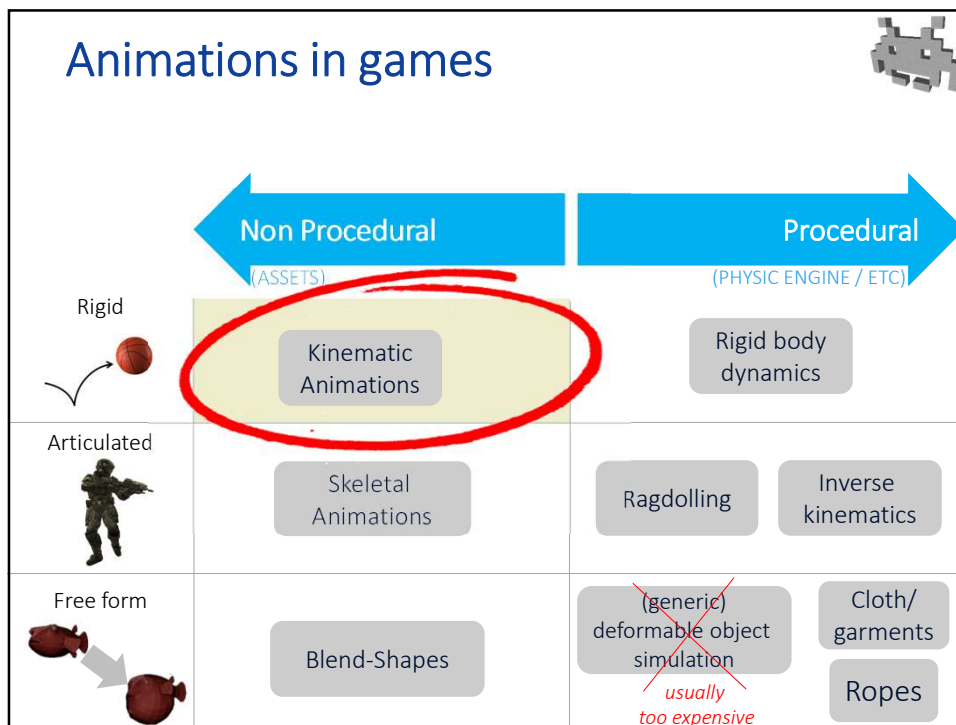
Animations in games: authored or procedural?

- Or... a mix
 - Example 1: *primary* animations: authored
secondary animations: physically generated
 - Example 2: *alive* characters: scripted
dead characters: physically generated (ragdolls)
 - Example 3: walk cycle: authored (skeletal animation)
feet placement: procedural (inverse kinematic)
 - Example 4: normal "behavior", e.g. sparring: authored
gaze control: scripted
 - Example 5: normal "behaviors" e.g. jumping, running
 modifications / transitions: AI generated
 - *and more*
- mixing AI with authored animations is a frontier in CG and Interactive techniques!

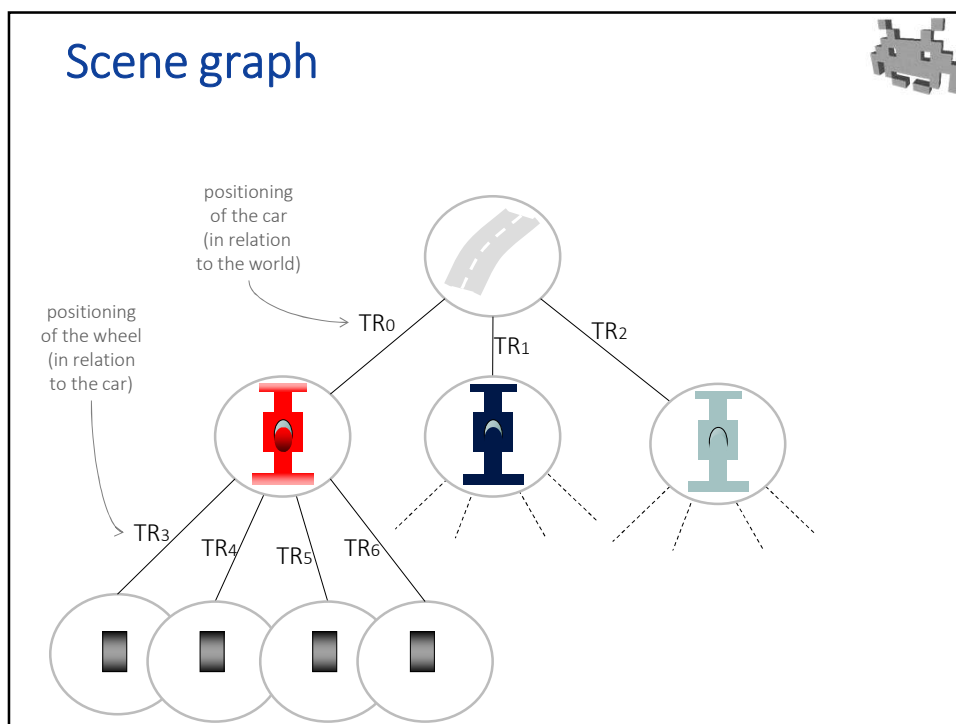
11



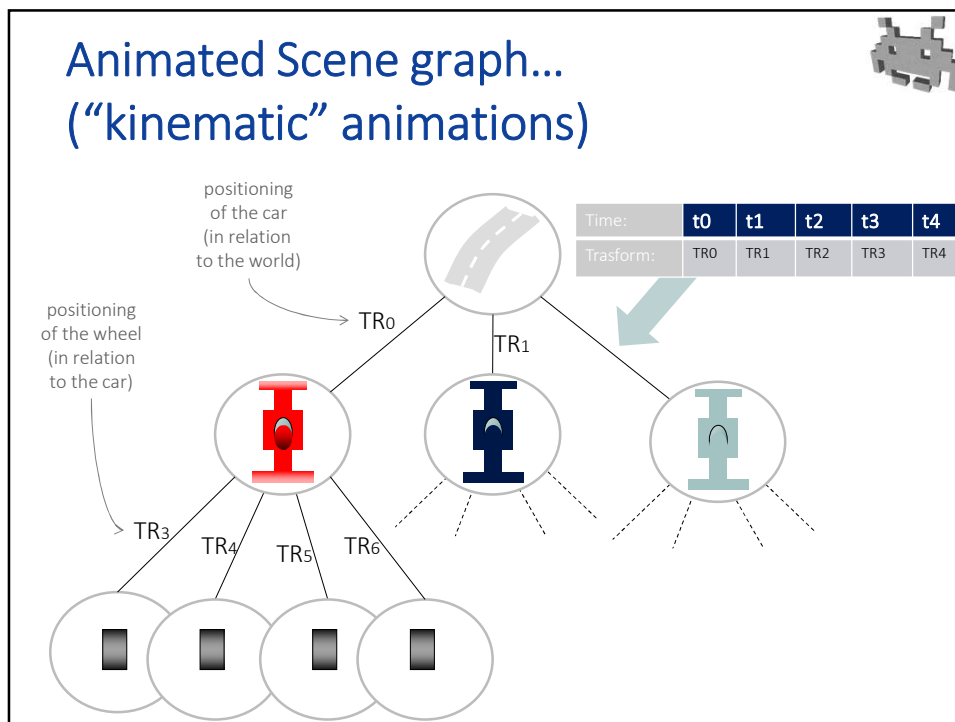
12



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Kinematic animations: how?

- way 1:
 - just scripting
- way 2:
 - editing in a animation software
 - cinema 4D, blender, 3D max, ...
 - (including use of I.K. as part of the interface)
 - export animation
 - as a sequence of **keyframes**
 - File formats: collada, fbx, ...

Time:	t0	t1	t2	t3	t4
A=>B:	TR0	TR1	TR2	TR3	TR4
B=>C:	TR0	TR1	TR2	TR3	TR4

asset:
the script

asset:
the animation

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Interpolating keyframes (applies to *all kinds* of asset animations)

- Keyframes
+
in-betweens (interpolation)

keyframe A $0.5 \cdot \text{keyframe A} + 0.5 \cdot \text{keyframe B}$ keyframe B

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Keyframe interpolation (for kinematic animations)

T_A $T_i = ?^*$ T_B

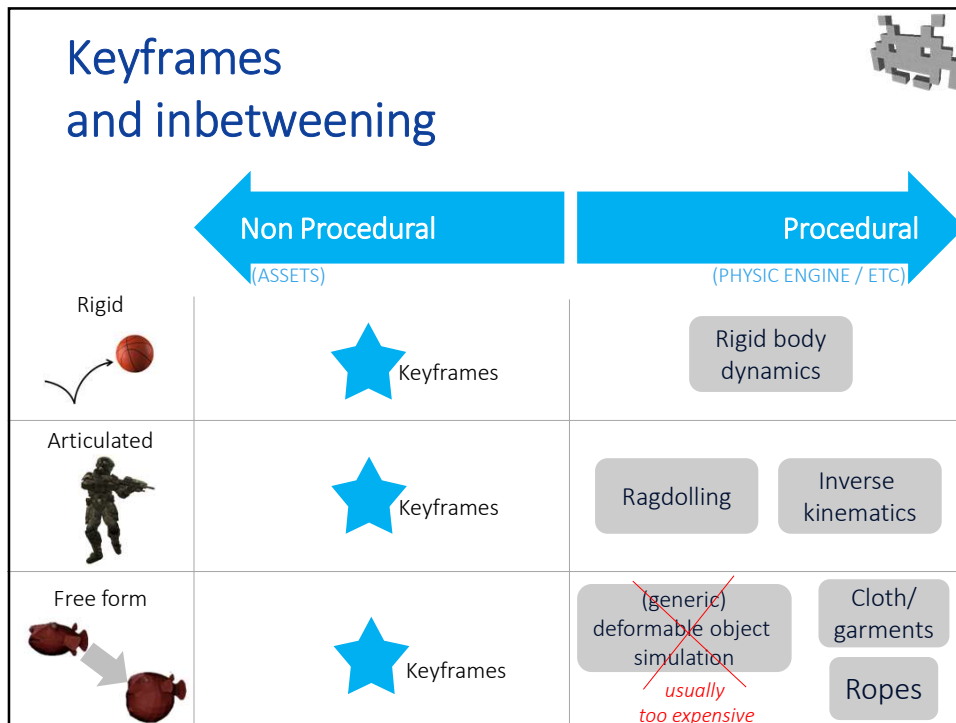
time A = 100
keyframe A

time curr. = 150
interpolated

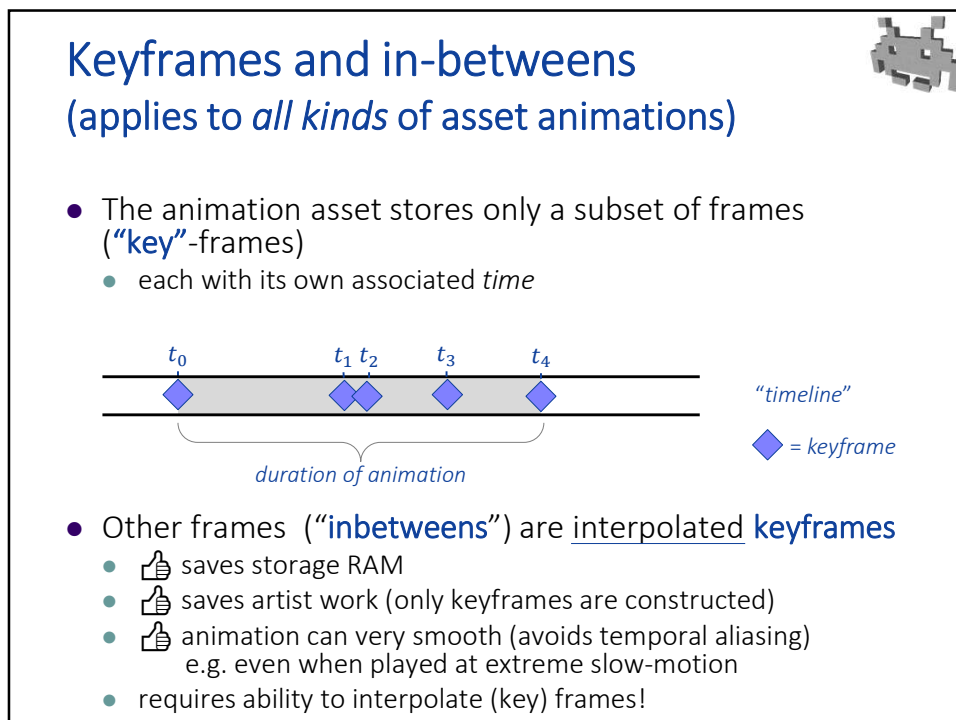
time B = 200
keyframe B

* $T_i = \text{mix}(T_A, T_B, 0.5)$

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Keyframes and in-betweens (applies to *all kinds* of asset animations)



- keyframes distribution can be *adaptive*
 - more keyframes only where needed
- inbetweening happens on demand
 - e.g. at each refresh rate of videoframe
- keyframe *times* can be at arbitrary
 - not necessarily exact frames, not necessarily integers
 - all frames shown on screen will be inbetweens
- the better the interpolation schema
→ better in-betweens → fewer keyframes are needed
- editing the animation: ← *asset*
 - editing individual keyframes
 - editing keyframe *times* (e.g. achieves non-linearity of speed)
 - pick a new time t_i (not a keyframe)
bake the inbetween at t as a new keyframe
edit it!

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Kinematic animations



- Just compute new transformations per frame
 - Often, just the rotation component
(translation is constant)
- Or store transformations per keyframe
 - Then, interpolate them for any other frame
between keyframes
- By cumulating the transformations in the graph, we can compute the final position of every node
 - This is called solving a “forward kinematic” problem
 - The inverse problem (from final position of certain nodes, compute the transform, especially the rotation) is called “inverse kinematic” (IK)

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“Forward Kinematic”

find c (and b), given a, α, β, k, h

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Inverse Kinematic (IK)

find α, β (and b), given a, c, k, h

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Inverse Kinematic (IK): for any number of joints

The diagram shows a 2-link IK chain. The first joint is a revolute joint at point a on a curved surface. The second joint is a slider joint at point b (red circle) on a horizontal line. The end effector is at point d . The links have lengths k and j . The distance between the slider joint and the end effector is h . The angles are α at joint a , β at joint b , and γ at joint c . The positions of the slider joint and the end effector are labeled $(b = ?)$ and $(c = ?)$ respectively.

solve for α, β, γ (and b, c), given a, d, k, h, j

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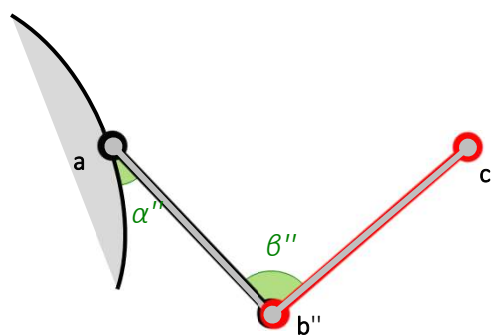
Inverse Kinematic (IK): an ambiguity

The diagram shows a 2-link IK chain. The first joint is a revolute joint at point a on a curved surface. The second joint is a revolute joint at point b' (red circle). The end effector is at point c (red circle). The links have lengths k and h . The angles are α' at joint a and β' at joint b' .

solve for α, β (and b), given a, c, k, h

30

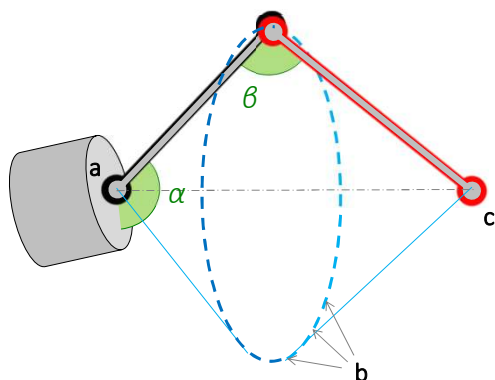
Inverse Kinematic (IK): an ambiguity



solve for α, β (and b), given a, c, k, h

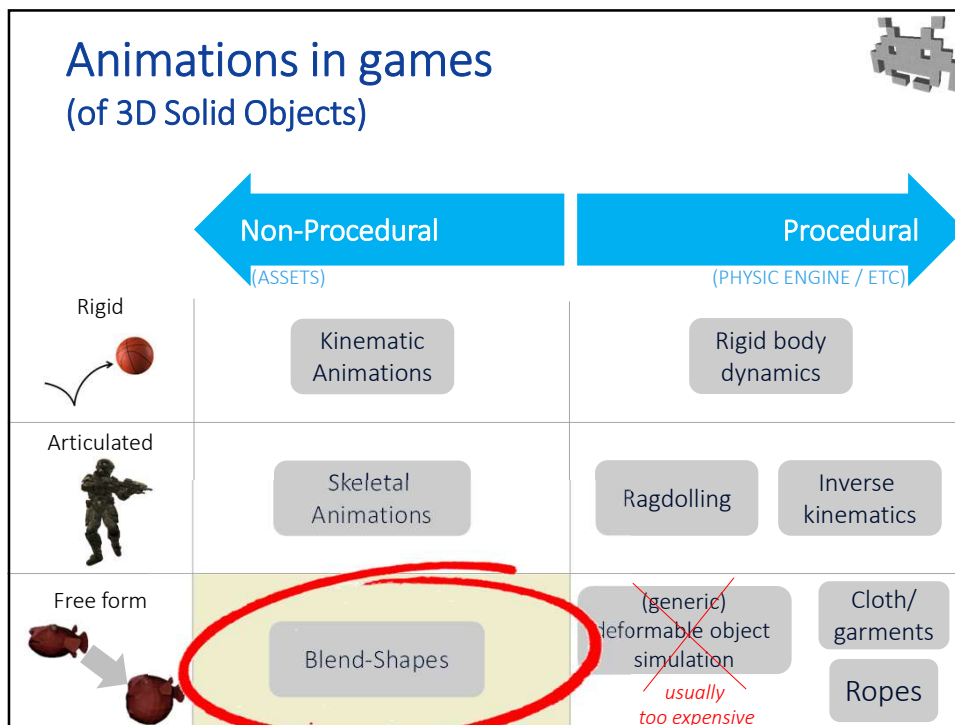
31

Inverse Kinematic (IK) in 3D: more ambiguities



solve for α, β (and b), given a, c, k, h

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Asset for free-form animations: Blend-shapes

- A.K.A:
 - Blend-shapes
 - Per-vertex animations
 - Vertex-animations
 - Face-morphs
 - Shape-keys
 - Morph-targets
 - ...

BARRY BLITT (THE NEW YORKER)

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Blend shapes: concept



Walk cycle
(Monkey Island
LucasArt 1991)

- Animation in 2D (old school) games:
a sequence of sprites
- Animation in 3D games:
just a sequence of meshes?

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Reminder: representation of a mesh



- **Indexed** mode :
 - Geometry: array of vertex positions
 - Attributes:
 - stored at vertices
 - Connectivity:
 - Array of triangles (or polygons)
 - Each triangle = a triplet of indexes to vertice

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Mesh (data structure)

connectivity (indexed)

Tri:	Wedge 1:	Wedge 2:	Wedge 3:
T1	V4	V1	V2
T2	V4	V2	V5
T3	V5	V2	V3

geometry:

Vert:	Pos
V1	(x,y,z)
V2	(x,y,z)
V3	(x,y,z)
V4	(x,y,z)
V5	(x,y,z)

attributes:

UV	Col
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)

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Blend shapes (data structure)

connectivity (indexed)

Tri:	Wedge 1:	Wedge 2:	Wedge 3:
T1	V4	V1	V2
T2	V4	V2	V5
T3	V5	V2	V3

geometries:

Vert:	Base Shape	Shape 1	Shape 2	...
V1	(x,y,z)	(x,y,z)	(x,y,z)	...
V2	(x,y,z)	(x,y,z)	(x,y,z)	...
V3	(x,y,z)	(x,y,z)	(x,y,z)	...
V4	(x,y,z)	(x,y,z)	(x,y,z)	...
V5	(x,y,z)	(x,y,z)	(x,y,z)	...

attributes:

UV	Col
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)
(u,v)	(r,g,b)

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Blend shapes



- A mesh with several associated geometries
 - I.e. a sequence of meshes ('shapes') with
 - shared connectivity
 - many shared attributes
 - except normals / tangents dirs
 - shared UV-map, per vertex colors...
 - different geometries
 - (and shared textures as well)
 - Variants (they are equivalent):
 - Relative mode:
 - *base shape*: stored as per-vertex positions (points)
 - any other *shape*: stored as difference with *base shape* (vectors)
 - Absolute mode:
 - each *shape* stored as per-vertex positions (points)
- aka 'morph'
aka (key)-'frame'
aka 'shape-key'

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Blend shapes (as a data structure, e.g. C++)



- Indexed mesh :

```
class Vertex {
    vec3 pos;
    rgb color;
    vec3 normal;
};

class Face{
    int vertexIndex[3];
};

class Mesh{
    vector<Vertex> vert; /* geom + attr */
    vector<Face> tris; /* connectivity */
};
```

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Blend shapes (as a data structure, e.g. C++)



- Blend-shape :

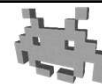
```
class Vertex {
    vec3 pos [ N_SHAPES ] ;
    rgb color;
    vec3 normal [ N_SHAPES ] ;
};

class Face{
    int vertexIndex[3];
};

class Mesh{
    vector<Vertex> vert; /* geom + attr */
    vector<Face> tris; /* connectivity */
};
```

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Blend-shapes: most common file formats



- Simple:
 - .MDS (“quake”, valve)
 - or, just store a sequence of meshes (es .OBJ)
 - making sure connectivity is coherent!
(vertex ordering = the same)
- Complex:
 - .DAE (Collada)
 - .FBX (Autodesk)

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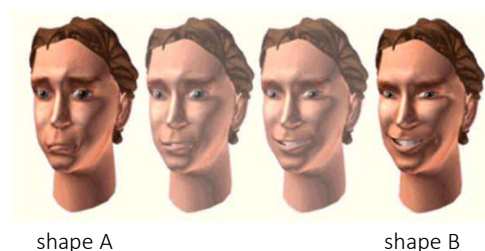
Blending shapes of a blend-shape



- Blending between two shape_A and shape_B :
 - with relative BlendShapes:
$$\text{shape}_{base} + w_A \cdot \text{delta_shape}_A + w_B \cdot \text{delta_shape}_B \cdot w_B$$
 - with w_A, w_B usually between 0 and 1
 - otherwise, it's an "exaggeration"
 - with absolute BlendShapes : (equivalently) (verify!)
$$(1 - w_A - w_B) \cdot \text{shape}_{base} + w_A \cdot \text{delta_shape}_A + w_B \cdot \text{delta_shape}_B$$
 - Note: it's an extrapolation if $0 \leq w_A, w_B, w_A + w_B \leq 1$
 - Otherwise, it-s an extrapolation
- It's trivial to extend to a blend of multiple shapes

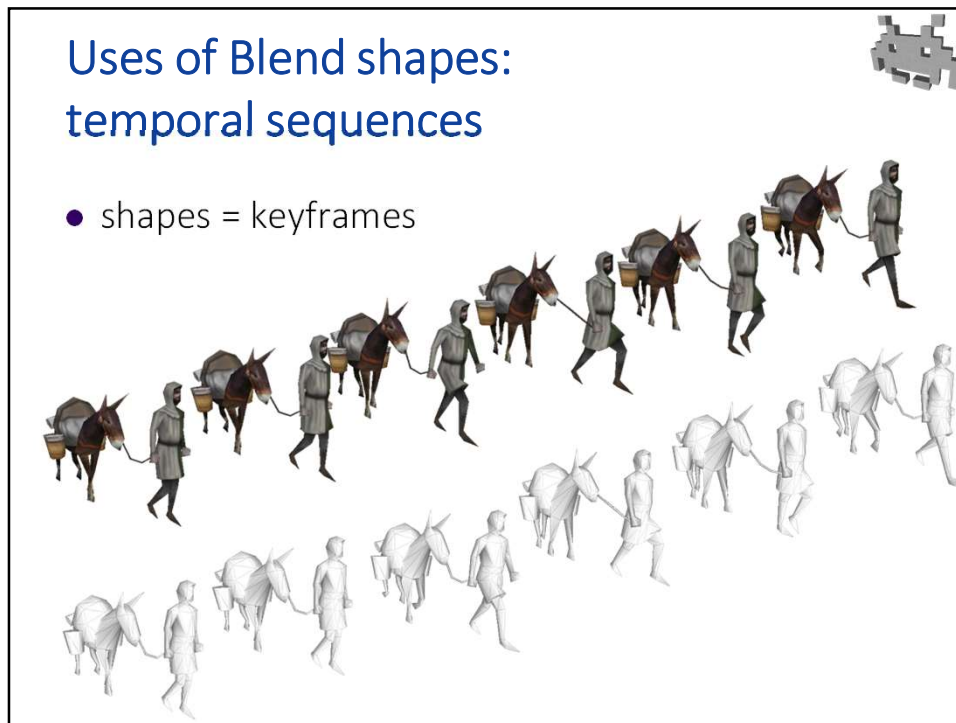
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Uses of Blend-Shapes: facial expressions

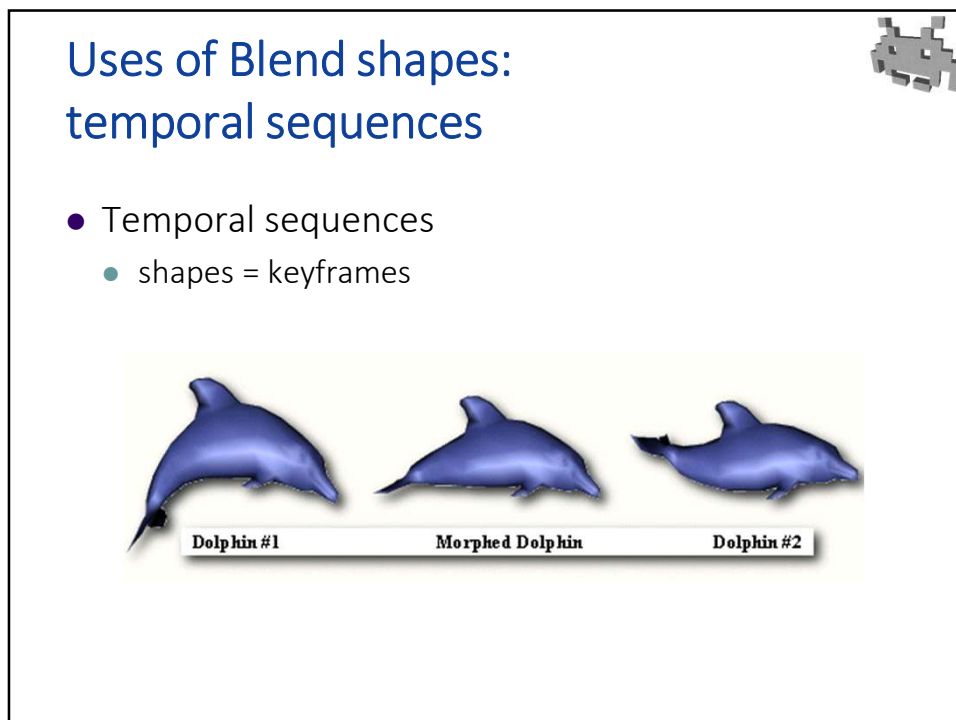


here: shapes = facial expressions
(typical use; that's why they are also called "face morphs")

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Blending keyframes of a temporal sequence

- shapes = keyframes of the animation
 - $shape_A$  with time t_A
 - $shape_B$  with time t_B
 - $shape_C$  with time t_C
 - $shape_D$  with time t_D
- given current time t with $t_B < t < t_C$
- then...
 - which shapes to blend? $shape_B$, $shape_C$
 - weights? $w_B = \frac{t - t_C}{t_B - t_C}$ $w_C = (1 - w_B) = \frac{t - t_B}{t_C - t_B}$

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Blending keyframes of a temporal sequence with transition functions

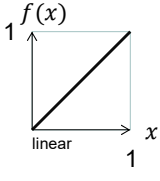
- shapes = keyframes of the animation
 - $shape_A$  with time t_A
 - $shape_B$  with time t_B
 - $shape_C$  with time t_C
 - $shape_D$  with time t_D
- given current time t with $t_B < t < t_C$
- then... *transition function*
 - which shapes to blend? $shape_B$, $shape_C$
 - weights? $w_B = f\left(\frac{t - t_C}{t_B - t_C}\right)$ $w_C = (1 - w_B)$

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














Transition functions

(applies to all animation types with keyframes)

- Not necessarily the Linear one



$f(x) = x$

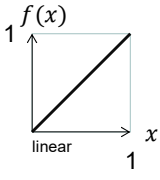
 easeIn	 easeOut	 easeInOut	 easeOutIn
 easeInBack	 easeOutBack	 easeInOutBack	 easeOutInBack
 easeInBounce	 easeOutBounce	 easeInOutBounce	 easeOutInBounce
 easeInElastic	 easeOutElastic	 easeInOutElastic	 easeOutInElastic

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














Transition functions


(applies to all animation types with keyframes)

- Not necessarily the Linear one



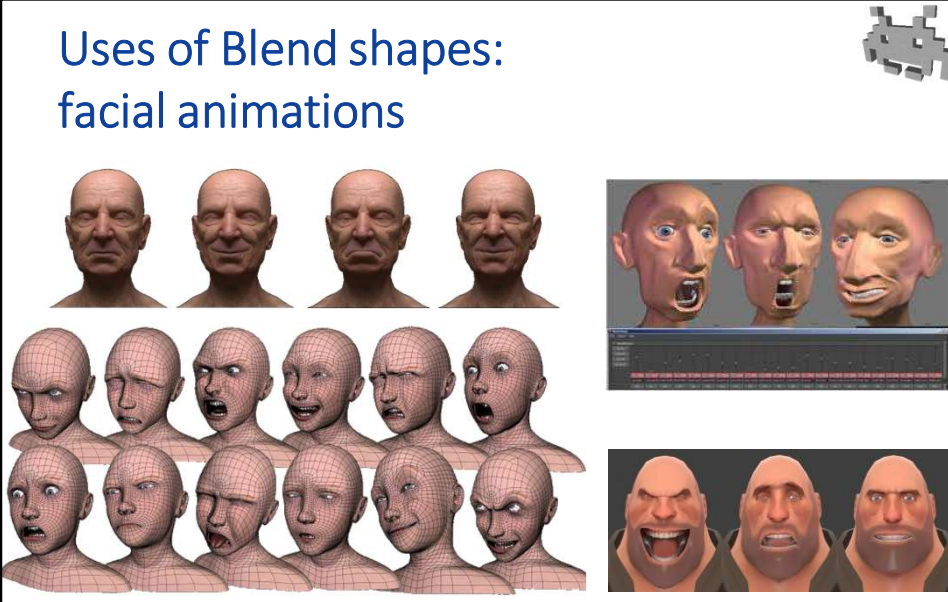
$f(x) = x$

 easeIn	 easeOut	 easeInOut	 easeOutIn
 easeInBack	 easeOutBack	 easeInOutBack	 easeOutInBack
 easeInBounce	 easeOutBounce	 easeInOutBounce	 easeOutInBounce
 easeInElastic	 easeOutElastic	 easeInOutElastic	 easeOutInElastic

NB:  = extrapolation !
i.e. exaggeration

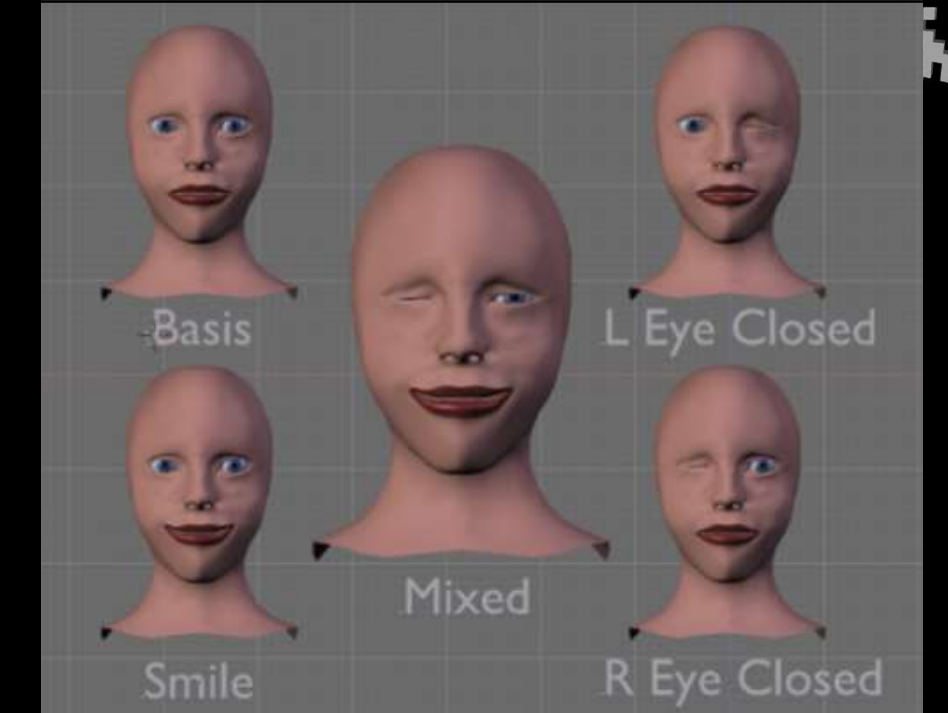
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Uses of Blend shapes: facial animations



Here, used together with skeletal animations (see next lecture)
(for mandible, neck, eyeballs)

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Basis

Smile

Mixed

L Eye Closed

R Eye Closed

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Using facial animations as Blend shapes



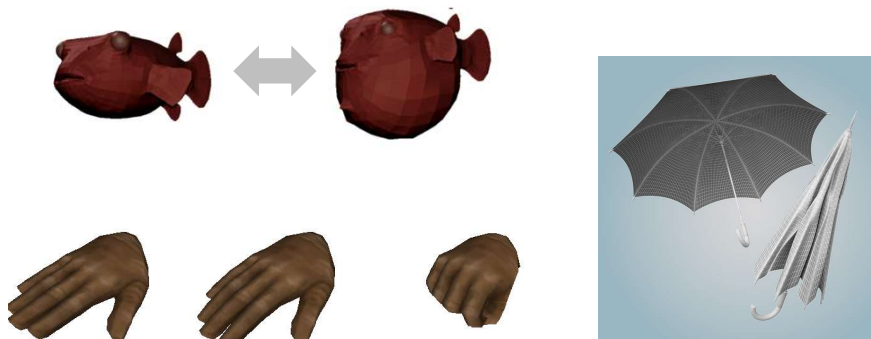
- 3D Modeller authors:
the set of blend-shapes
- Animator (of expressions) picks:
weights
 - eg.: with sliders
 - assisted / substituted by automatisms
 - lip sync
 - dynamically determined expressions
- Keyshape Blending: by rendering engine

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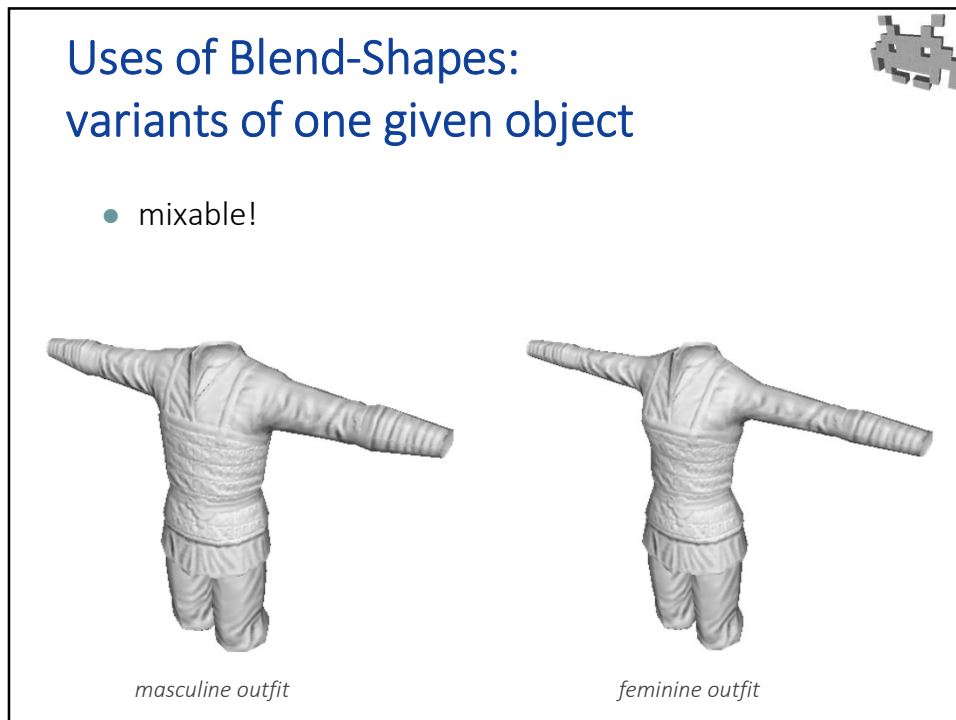
Uses of Blend-Shapes: generic deformations



- Baked poses



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Uses of Blend-Shapes



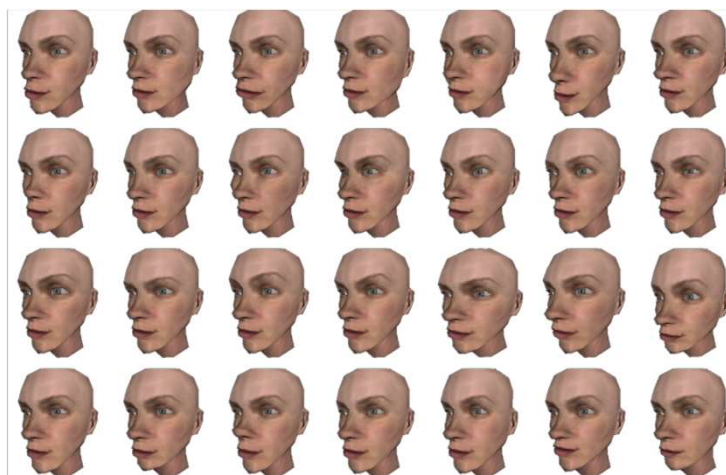
- Defines shapes of a class of objects
 - get a shape in the class = just choose the weights
 - 3D modelling at a high-level of abstraction
 - the weights “span” one **shape space**
 - one given shape = one point in the space
 - weights = coords
 - the space is the more useful the more:
 - *all and only* the reasonable shapes are represented in the space
- Typical Example: face morphologies
 - “face-space”
 - note: face morphology \neq facial expression

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Uses of Blend shapes



- A **blend shape** modelling a **face space** (“face-morphs”)

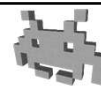


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What a blend shape

cannot do

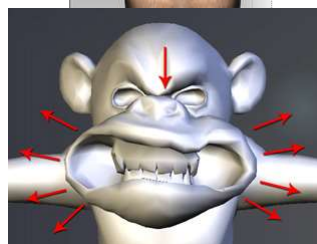
- Change connectivity
 - eg. change mesh res, remeshing
- Change topology
 - breaking apart, fusing parts
- Change most attributes
 - eg color, UV-map...
- Change textures
 - Use a [texture animation](#) instead?



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Blend shapes: authoring

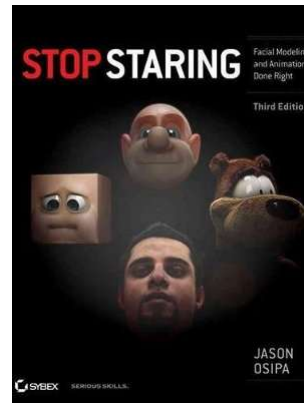
1. Editing base shape
 - including:
 - uv-mapping, texturing, etc.
2. Re-edit it
for each shape-key!
...while preserving:
connectivity,
textures, etc:
 - with low poly editing
 - or with subdivision surfaces...
 - or with parametric surfaces...
 - or with sculpting.



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Blend shapes: authoring

- Handbook for blend-shape based face animation:
 - “Stop Staring” (3d edition)
Jason Osipa
 - Covers: style, expression...
 - Non technical (high level)
 - Not about specific tools e.g. Blender, Maya




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Blend shapes: hot to obtain them

- Capture:
 - 3D acquisition of base shape B0
 - (including: simplification, remeshing, uv-mapping, etc)
 - capture subsequent shapes B1, B2...
 - e.g. real-time (kinect), o 3D scanning for each shape
 - compute a morph B0 => B1
 - “non rigid mesh alignment”


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Blend shapes: pros and cons



- During authoring:
 - 👍 flexible, expressive, huge number of DOF... (too many?)
 - 🗨️ work intensive to construct
 - 🗨️ expensive to store
- During use (by animator)
 - 👍 easy to use (just define global weights)
 - 🗨️ RAM cost
 - 🗨️ very little degree of freedoms (too few?)

but, not as bad as old sprites,




because

- (1) shared of connectivity, textures, attributes
- (2) keyframes / inbetweens!

Diagram description: A callout box on the right contains text and three pixelated character sprites. Three grey arrows point from the callout box to the 'work intensive to construct', 'expensive to store', and 'RAM cost' items in the list.

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Blend shapes: open challenges



- Capturing:
 - from a stream of meshes
 - e.g. : from a RGBD camera (like Microsoft Kinect) to a blend-shape: difficult!
- Compression
 - e.g.: reduce number of keyframes
- Streaming
 - server sends animation to client while it runs
- LOD-ding
 - like for meshes (but more difficult)

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